

LECTURES ON THEORY OF NUMBERS



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Chapter 1

Theory of Divisibility

1.1 Divisibility

Definition 1.1.1 (Natural Number). A number used for counting is said to be a natural number. The set of natural numbers is denoted and defined by $\mathbb{N} = \{1, 2, 3, 4, 5, \dots\}$.

Definition 1.1.2 (Integer). Any whole number positive, negative, or zero is said to be an integer. The set of integers is denoted and defined by $\mathbb{Z} = \{\dots, -3, -2, -1, 0, 1, 2, 3, \dots\}$.

Definition 1.1.3 (Divisibility). A number b is said to be divisible by a number a ($a \neq 0$) if there is a number c such that $b = ac$. We denote this by $a \mid b$, read as a divides b . If no such integer can be found we write $a \nmid b$, read as a does not divide b .

Example 1.1.1. (1) $3 \mid 12$ because $12 = 3 \cdot 4$

(2) $3 \nmid 7$ because there is no integer c such that $7 = 3 \cdot c$.

If $a \mid b$, then a is called a divisor of b and b is called a multiple of a . If $a \mid b$ and $0 < a < b$, then a is called a proper divisor or factor of b . We have $b = a \cdot c = (-a) \cdot (-c)$. Thus if $a \mid b$, then $-a \mid b$. For practical purposes we can limit our attention to only positive divisors of integers. 1 is a divisor of any integer and 0 is a multiple of any integer. Any non-zero integer is a divisor or multiple of itself.

Definition 1.1.4 (even number and odd number). A number which is multiple of 2 is called an even number, otherwise it is called an odd number.

Theorem 1.1.1. For any integer a, b, c the following hold:

(i) $a \mid b \Rightarrow a \mid bc$

(ii) $a \mid b$ and $b \mid c \Rightarrow a \mid c$

(iii) $a \mid b$ and $b \mid a \Rightarrow a = \pm b$

(iv) $a \mid 1 \Rightarrow a = \pm 1$

(v) $a \mid b$ and $a \mid c \Rightarrow a \mid (bx + cy)$ for any integers x and y .

The sum, difference, and product of two integers are obviously integers but the **quotient** of two integers may or may not be an integer.

Theorem 1.1.2 (Fundamental Theorem of Divisibility). *For any integers $a, b (b \neq 0)$, there exist unique integers q and r such that*

$$a = qb + r, \quad 0 \leq r < |b|.$$

Proof. The integer a lies between two consecutive integers of the sequence

$$\dots, -2|b|, -|b|, 0, |b|, 2|b|, \dots$$

So WLOG we may assume that $q|b| \leq a < (q+1)|b|$. Then $a - q|b| \geq 0$ and $a - q|b| < |b|$.

Let $a - q|b| = r$. Then $0 \leq r < |b|$ implies that

$$\begin{aligned} a &= qb + r && \text{when } b > 0 \\ &= (-q)b + r && \text{when } b < 0 \end{aligned}$$

Hence the existence of q and r is proved.

For uniqueness, let $a = q_1b + r_1$, $0 \leq r_1 < |b|$. Then $qb + r = a = q_1b + r_1$, $0 \leq |r_1 - r| < |b|$.

$$\begin{aligned} &\Rightarrow (q - q_1)b = r_1 - r \\ &\Rightarrow |q - q_1||b| = |r_1 - r| \\ &\Rightarrow |q - q_1||b| < |b| \\ &\Rightarrow |q - q_1| < 1 \end{aligned}$$

Since q and q_1 are both integers, so the above relation hold if $q - q_1 = 0 \Rightarrow q = q_1$.

Consequently, $0 = r_1 - r \Rightarrow r = r_1$.

Thus, q and r are unique.

Hence the theorem. ■

Definition 1.1.5 (Prime number). *Any integer p which exceeds unity is called a prime if it has no integral divisors except $\pm p$ and ± 1 .*

For example 2, 3, 5, etc. are primes.

Definition 1.1.6 (Composite number). An integer $c > 1$ which has divisors other than $\pm c$ and ± 1 is called a composite number.

For example 6, 30, 45, etc. are composite numbers.

Note. 1 is neither prime nor composite.

1.2 Greatest Common Divisor and Least Common Multiple

Definition 1.2.1 (Greatest Common Divisor(g.c.d.)). The greatest integer g that divides both of two integers a and b is called the g.c.d. of a and b and is denoted by $(a, b) = g$.

For example $(20, 30) = 10$, $(-6, 9) = 3$. Note that $(a, b) \geq 1$, $(a, 0) = |a|$, $(0, 0) = \infty$ and, $(a, a) = a$ for any integer $a \neq 0$.

Definition 1.2.2 (Relatively prime). If $(a, b) = 1$ then the integers a and b are called relatively prime or co-prime.

Theorem 1.2.1 (Euclidean Algorithm(330-275 B.C.)). Let a and b be two positive integers where $b \nmid a$. Let $r_0 = a$, $r_1 = b$ and apply the division algorithm repeatedly to obtain a set of remainders $r_2, r_3, \dots, r_n, r_{n+1}$ defined successively by the relations:

$$\begin{aligned} r_0 &= q_1 r_1 + r_2, & 0 < r_2 < r_1 \\ r_1 &= q_2 r_2 + r_3, & 0 < r_3 < r_2 \\ r_2 &= q_3 r_3 + r_4, & 0 < r_4 < r_3 \\ \dots & \dots \dots \dots \dots \\ r_{n-2} &= q_{n-1} r_{n-1} + r_n, & 0 < r_n < r_{n-1} \\ r_{n-1} &= q_n r_n + r_{n+1}, & \text{where } r_{n+1} = 0. \end{aligned}$$

Then r_n , the last nonzero remainder in this process, is (a, b) , the g.c.d. of a and b .

Proof. Since $r_1, r_2, \dots, r_{n+1}$ are decreasing and nonnegative, so there is a stage at which $r_{n+1} = 0$. The last relation $r_{n-1} = q_n r_n$ shows that $r_n \mid r_{n-1}$ and hence the penultimate relation implies that $r_n \mid r_{n-2}$. By induction we see that $r_n \mid r_i, \forall i$. In particular, $r_n \mid r_1 = b$ and $r_n \mid r_0 = a$, so r_n is a common divisor of a and b .

Now let d be any common divisor of a and b . Then $d \mid a = r_0$ and $d \mid b = r_1$. The definition of r_2 shows that $d \mid r_2$. The next relation shows that $d \mid r_3$. By induction, $d \mid r_i, \forall i$, so $d \mid r_n$. This shows that $r_n = d$.

Hence r_n is the required g.c.d. of a and b . ■

The following theorem states that the g.c.d. of any two integers can be expressed as an integral linear combination of them.

Theorem 1.2.2. *If $g = (a, b)$, then there exists integers x and y such that $g = ax + by$.*

Proof. Consider the linear combinations $au + bv$, where $u, v \in \mathbb{Z}$. This set of integers includes positive and negative values, and 0 by the choice of $u = v = 0$. Choose x and y so that $ax + by$ is the least positive integer l in the set. Thus $ax + by = l$.

Now we prove that $l \mid a$ and $l \mid b$. Suppose that $l \nmid a$. Then there exist integers q and r such that

$$a = ql + r, \quad 0 < r < l.$$

$$\Rightarrow r = a - ql = a - q(ax + by) = a(1 - qx) + b(-qy).$$

Thus r is in the set $\{au + bv\}$. This contradicts the fact that l is the least positive integer in the set $\{ax + by\}$. Thus $l \mid a$. Similarly, we can show that $l \mid b$.

Now, since g is the g.c.d. of a and b , we may write $a = gA$, $b = gB$, and $l = ax + by = g(Ax + By)$. Thus, $g \mid l$ and so we conclude that $g \leq l$. Now $g < l$ is impossible as g is the g.c.d. of a and b . Thus, $g = l = ax + by$. ■

Corollary 1.2.3. $(a, b) = 1 \iff \exists x, y \in \mathbb{Z}$ such that $ax + by = 1$.

Example 1.2.1. 1. Find the g.c.d. of 1769 and 2378 using Euclidean algorithm

2. Hence express it as an integral linear combination of these numbers.

Solution: 1. We have:

$$2378 = 1 \cdot 1769 + 609$$

$$1769 = 2 \cdot 609 + 551$$

$$609 = 1 \cdot 551 + 58$$

$$551 = 9 \cdot 58 + 29$$

$$58 = 2 \cdot 29$$

Hence by the Euclidean algorithm $(1769, 2378) = 29$.

2. Now

$$\begin{aligned} 29 &= 551 - 9 \cdot 58 \\ &= 551 - 9 \cdot (609 - 1 \cdot 551) \\ &= 10 \cdot 551 - 9 \cdot 609 \\ &= 10(1769 - 2 \cdot 609) - 9 \cdot 609 \\ &= 10 \cdot 1769 - 29 \cdot 609 \\ &= 10 \cdot 1769 - 29 \cdot (2378 - 1 \cdot 1769) \\ &= 39 \cdot 1769 + (-29) \cdot 2378 \end{aligned}$$

$$\therefore 29 = 39 \cdot 1769 + (-29) \cdot 2378.$$

Definition 1.2.3 (Least Common Multiple). *The least common multiple (l.c.m.) of two or more non zero integers is the smallest positive integer that is divisible by all of them. If l is the l.c.m. of a and b , we denote it by $[a, b] = l$.*

For example $[20, 30] = 60$. Note that there is no greatest common multiple of two or more integers. Also observe that g.c.d. and l.c.m. are unique.

Theorem 1.2.4. *If $ab > 0$, then $a, b = ab$.*

Proof. Let $[a, b] = l$ and $(a, b) = g$. Then $a \mid l$ and $b \mid l$ gives $ab \mid la$ and $ab \mid lb$

$$\therefore ab \mid (la, lb)$$

$$\Rightarrow ab \mid l(a, b)$$

$$\Rightarrow ab \mid lg \quad \cdots (1)$$

On the other hand, since $a \mid \frac{ab}{g}$ and $b \mid \frac{ab}{g}$, so $\frac{ab}{g}$ is a common multiple of a and b . Therefore, $l \mid \frac{ab}{g} \Rightarrow lg \mid ab \quad \cdots (2)$ From (1) and (2) we conclude that $lg = ab \Rightarrow a, b = ab$. ■

Note. $[a, b] \mid abm$ where m is an integer, that is, l.c.m. of any two or more integers divides any common multiple of them.

Theorem 1.2.5. *Let p be a prime and a be any integer. Then either $p \mid a$ or $(a, p) = 1$.*

Proof. If $p \mid a$, then there is nothing to prove. If $p \nmid a$, then we shall prove that $(a, p) = 1$. Let $(a, p) = g$. Then $g \mid a$ and $g \mid p$. But p is a prime, so $g \mid p$ gives $g = 1$ or $g = p$. If $g = p$, then $g \mid a \Rightarrow p \mid a$, which is not possible.

Hence $g = 1$ and $(a, p) = 1$. ■

Theorem 1.2.6. *If p is a prime and $p \mid ab$, then $p \mid a$ or $p \mid b$.*

Proof. If $p \mid a$, then there is nothing to prove. If $p \nmid a$, then $(a, p) = 1$. Since $p \mid ab$ and $(a, p) = 1$, so $p \mid b$. ■

Theorem 1.2.7 (Euclid's Lemma). *If $a \mid bc$ and $(a, b) = 1$, then $a \mid c$.*

Proof. Since $(a, b) = 1$, there exist integers x and y such that

$$ax + by = 1.$$

Since $a \mid bc \Rightarrow bc = am, m \in \mathbb{Z}$.

$$\therefore c = c \cdot 1 = c(ax + by) = acx + bcy$$

$$= acx + amy$$

$$= a(cx + my)$$

$$\Rightarrow a \mid c$$

■

1.3 Factorization in Prime Numbers

Theorem 1.3.1 (Fundamental Theorem of Arithmetic or Unique Factorization Theorem). *Every positive integer $N > 1$ can be expressed product of primes in one and only one way if we do not distinguish between two same prime factors.*

Proof. Let $p_1 > 1$ be the least divisor of N . Then $p_1 < N$. Evidently, p_1 is a prime. We write $N = p_1 N_1$. If N_1 is a prime, N has been expressed as a product of two primes not necessarily distinct.

If N_1 is composite, its least divisor $p_1 > 1$ is a prime. We write $N_1 = p_2 N_2$, and proceed with N_2 as before. After a finite number of such steps we obtain a factorization

$$N = p_1 p_2 p_3 \cdots p_n$$

of N into primes. Suppose that

$$N = q_1 q_2 q_3 \cdots q_r$$

is a second factorization of N .

Then the prime q_1 evidently divides one of the primes p_i , say p_1 . Hence $q_1 = p_1$ and $q_2 q_3 \cdots q_r = p_2 p_3 \cdots p_n$. Similarly q_2 is equal to one of the factors on the right, say p_2 . Proceeding in this manner we conclude that $r = n$ and that $q_1, q_2, q_3, \cdots, q_r$ are identical with $p_1, p_2, p_3, \cdots, p_n$ in some order. ■

Corollary 1.3.2. *An integer $n > 1$ can be uniquely written as $n = p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3} \cdots p_k^{\alpha_k}$ where $p_1, p_2, p_3, \cdots, p_k$ are distinct primes and $\alpha_1, \alpha_2, \alpha_3, \cdots, \alpha_k$ are positive integers.*

Proof. By [Theorem 1.3.1](#) we have

$$n = p_1 p_2 p_3 \cdots p_r$$

Since the prime factors are not necessarily distinct, by collecting the same primes we can write the above equation as

$$n = p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3} \cdots p_k^{\alpha_k}.$$

■

This representation is called the [canonical representation](#) or the [standard representation](#) or the [standard factorization](#) of n .

Motivation:. $N = 2 \cdot 3 \cdot 5 = 30$

$P = N + 1 = 30 + 1 = 31$, not divisible by the prime in the composition of P .

Theorem 1.3.3 (Euclid). *The number of primes is infinite.*

Proof. Let there are only a finite number of primes, say $p_1, p_2, p_3, \cdots, p_k$, where p_k is the largest prime. We define

$$N = p_1 p_2 p_3 \cdots p_k$$

$$\Rightarrow N + 1 = p_1 p_2 p_3 \cdots p_k + 1$$

$$\Rightarrow P = p_1 p_2 p_3 \cdots p_k + 1, \text{ where } P = N + 1.$$

Now if P is a prime then p_k is not the largest prime. If P is not a prime, then by Fundamental Theorem of Arithmetic, P can be factored into prime factors. So there exist a prime p such that $p \mid P$.

Since there are only prime $p_1, p_2, p_3, \cdots, p_k$, so p will be one of them, say $p = p_i$, $1 \leq i \leq k$. Now $p \mid P \Rightarrow p_i \mid P$, but this impossible by definition of P . Hence it is a contradiction. Thus the number of primes is infinite. ■

Example 1.3.1. *Show that one of the two consecutive integers is divisible by 2.*

Solution: Let the two consecutive integers be $n, n + 1$. If n be odd, then $n + 1$ is even and is divisible by 2. If n is even then it is divisible by 2.

Example 1.3.2. Show that one of the three consecutive integers is divisible by 3.

Solution: Let $n, n+1, n+2$ be any three consecutive integers. Here n must be any one of the forms $3m, 3m+1, 3m+2$. When $n = 3m$, the first integer is divisible by 3, when $n = 3m+1$, $n+2 = 3m+3$ which is divisible by 3, when $n = 3m+2$, $n+1 = 3m+3$ which is divisible by 3.

Example 1.3.3. Show that the product of any three consecutive integers is divisible by 6.

Solution: Let n be any integers. Then $n(n+1)(n+2)$ is divisible by 6.

Example 1.3.4. If $2^p - 1$ is a prime, then show that p is itself a prime.

Solution: Suppose that p is not a prime. Then it is composite, say $p = ab$. Then $2^p - 1 = 2^{ab} - 1 = (2^a)^b - 1$ which is divisible by $2^a - 1$. So, $2^{ab} - 1$ or $2^p - 1$ is a composite number which contradicts our given assumption.

So p must be a prime.

Example 1.3.5. If $2^n + 1$ is a prime, then n is a power of 2.

Solution: If n is not a power of 2, then suppose that $n = 2^m \times q$ where q is odd and greater than 1. Now $2^{2^m \times q} + 1 = (2^{2^m})^q + 1$ which is divisible by $2^{2^m} + 1$. This contradicts that $2^n + 1$ is a prime. Hence n must be a power of 2.

$$\begin{array}{rcl} a^5 & - & \\ 1 & = & \\ (a-1) & & \\ (a^4 + & & \\ a^3 + 1) & & \end{array}$$

1. If $a = qb + r$ then prove that $(a, b) = (b, r)$.

2.

Chapter 2

Arithmetic Functions and Diophantine Equations

2.1 Arithmetic Functions

Definition 2.1.1 (Arithmetic Function). A function $f : \mathbb{N} \rightarrow \mathbb{C}$, whose domain is the set of natural numbers and range is the subset of the set of complex numbers, is called the arithmetic function, number theoretic function or numerical function.

Definition 2.1.2 (Totally Multiplicative Function). An arithmetic function f is called completely multiplicative or totally multiplicative if $f(ab) = f(a)f(b)$. Again f is called *multiplicative* if $f(ab) = f(a)f(b)$ where $(a, b) = 1$. If f is multiplicative then $f(1) = 1$.

Definition 2.1.3. The function

$$\tau : \mathbb{N} \rightarrow \mathbb{N} \text{ defined by } \tau(n) = \sum_{\substack{d|n \\ d \geq 1}} 1$$

denotes the number of all positive divisors of n , where n is a positive integer.

Note. Some authors write $d(n)$ for $\tau(n)$.

Definition 2.1.4. The function

$$\sigma : \mathbb{N} \rightarrow \mathbb{N} \text{ defined by } \sigma(n) = \sum_{\substack{d|n \\ d \geq 1}} d$$

denotes the sum of all positive divisors of n , where n is a positive integer.

Definition 2.1.5. The function

$$P : \mathbb{N} \rightarrow \mathbb{N} \text{ defined by } P(n) = \prod_{\substack{d|n \\ d \geq 1}} d$$

denotes the product of all positive divisors of n , where n is a positive integer.

Definition 2.1.6. The function

$$\sigma_k : \mathbb{N} \rightarrow \mathbb{N} \text{ defined by } \sigma_k(n) = \sum_{\substack{d|n \\ d \geq 1}} d^k$$

denotes the sum of the k -th powers of the divisors of n , where n is a positive integer.

Example 2.1.1. Let $n=6$. The divisors of 6 are $d : 1, 2, 3, 6$.

$$\sigma_1(n) = \sigma(n) = \sum_{d|n=6} d = 1 + 2 + 3 + 6 = 12$$

$$\sigma_0(n) = 1^0 + 2^0 + 3^0 + 6^0 = 1 + 1 + 1 + 1 = 4 = \tau(n)$$

$$\sigma_3(n) = \sum_{d|n=6} d^3 = 1^3 + 2^3 + 3^3 + 6^3 = 1 + 8 + 27 + 216 = 252$$

Remark. If n is a prime, then n has only two positive divisors, 1 and n itself.

$$\therefore \tau(n) = 2, \sigma(n) = n + 1, \text{ and } P(n) = n.1 = n$$

Definition 2.1.7 (Euler's ϕ function). Let $n \geq 1$ be a positive integer. Then $\phi(n)$ denotes the number of numbers not exceeding n , which are relatively prime to n . This $\phi(n)$ is called Euler's ϕ function.

Example 2.1.2. The functions τ, σ, σ_k , and ϕ are all arithmetic functions.

Example 2.1.3. Following table lists $\tau(n), \sigma(n)$ and $P(n)$ for $n = 1, 2, 3, \dots, 10$.

n	1	2	3	4	5	6	7	8	9	10
$\tau(n)$	1	2	2	3	2	4	2	4	3	4
$\sigma(n)$	1	3	4	7	6	12	8	15	13	18
$P(n)$	1	2	3	8	5	36	7	64	27	100
$\phi(n)$	1	1	2	2	4	2	6	4	6	4

$$\tau(n), \sigma(n), P(n), \text{ and } \phi(n)$$

Definition 2.1.8 (Gauss Function(Greatest Integer Function)). Let x be a real number. Then we denote by $[x]$, the greatest integer not greater than x , and call it a Gauss function.

Example 2.1.4. $[5] = 5, \quad [5.25] = 5, \quad \left[\frac{1}{5}\right] = 0, \quad \left[\frac{-3}{2}\right] = -2, \quad [\pi] = 3,$
 $[x] = [[x]]$

For each real number x , we can write

$$x = [x] + a, \text{ where } 0 \leq a < 1$$

Here $[x]$ and a are respectively called the integral and fractional part of x .

Theorem 2.1.1 (Goldbach Conjecture). This states that every even integer bigger than 2 is the sum of two primes.

Example 2.1.5.

$$\begin{aligned}
4 &= 2 + 2 \\
6 &= 3 + 3 \\
8 &= 3 + 5 \\
10 &= 3 + 7 \\
50 &= 3 + 47 \\
100 &= 29 + 71
\end{aligned}$$

It is an unsolved problem. Goldbach verified up to 1,00,000 at least.

Now let us provide the general formulae for τ and σ when n is a composite number as follows:

Theorem 2.1.2. *If $n = p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3} \cdots p_k^{\alpha_k}$ where $p_1, p_2, p_3, \dots, p_k$ are distinct primes and $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_k$ are positive integers, then*

$$(i) \quad \tau(n) = (\alpha_1 + 1)(\alpha_2 + 1) \cdots (\alpha_k + 1) = \prod_{i=1}^k (\alpha_i + 1)$$

$$(ii) \quad \sigma(n) = \frac{p_1^{\alpha_1+1} - 1}{p_1 - 1} \cdot \frac{p_2^{\alpha_2+1} - 1}{p_2 - 1} \cdots \frac{p_k^{\alpha_k+1} - 1}{p_k - 1} = \prod_{i=1}^k \frac{p_i^{\alpha_i+1} - 1}{p_i - 1}$$

Proof. We shall prove the theorem by induction on k . Let $k = 1$, that is, n has only one prime factor, say $n = p^\alpha$, where α is a positive integer. Then the positive divisors of n are $1, p, p^2, \dots, p^\alpha$. We have

$$\tau(n) = \alpha + 1 \text{ and } \sigma(n) = 1 + p + p^2 + \cdots + p^\alpha = \frac{p^{\alpha+1} - 1}{p - 1}$$

Next suppose that (i) and (ii) hold when n has $k - 1$ distinct prime factors ($k \geq 2$). Write $n = n' p_k^{\alpha_k}$ where $n' = p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3} \cdots p_{k-1}^{\alpha_{k-1}}$, $(n', p_k^{\alpha_k}) = 1$, and all p 's are distinct primes. Moreover, any divisor of n' is a divisor of n . Hence any divisor of n is of the form $d' p_k^t$, $0 \leq t \leq \alpha_k$, $d' \geq 1$, $d' \mid n'$.

$$\begin{aligned}
\tau(n) &= \sum_{\substack{d \mid n \\ d \geq 1}} 1 \\
&= \sum_{d' \mid n} 1 + \sum_{d' p_k \mid n} 1 + \sum_{d' p_k^2 \mid n} 1 + \cdots + \sum_{d' p_k^{\alpha_k} \mid n} 1 \\
&= \underbrace{\tau(n') + \tau(n') + \tau(n') + \cdots + \tau(n')}_{\alpha_k + 1 \text{ terms}} \\
&= \tau(n')(\alpha_k + 1)
\end{aligned}$$

By induction hypothesis we have $\tau(n') = (\alpha_1 + 1)(\alpha_2 + 1) \cdots (\alpha_{k-1} + 1)$

$$\therefore \tau(n) = (\alpha_1 + 1)(\alpha_2 + 1) \cdots (\alpha_{k-1} + 1)(\alpha_k + 1) = \prod_{i=1}^k (\alpha_i + 1)$$

$$\begin{aligned} \sigma(n) &= \sum_{\substack{d|n \\ d \geq 1}} d \\ &= \sum_{\substack{d'|n' \\ d' \geq 1}} d' + \sum_{\substack{d'|n' \\ d' \geq 1}} d' p_k + \cdots + \sum_{\substack{d'|n' \\ d' \geq 1}} d' p_k^{\alpha_k} \\ &= \left(\sum_{\substack{d'|n' \\ d' \geq 1}} d' \right) + \left(\sum_{\substack{d'|n' \\ d' \geq 1}} d' \right) p_k + \cdots + \left(\sum_{\substack{d'|n' \\ d' \geq 1}} d' \right) p_k^{\alpha_k} \\ &= \left(\sum_{\substack{d'|n' \\ d' \geq 1}} d' \right) (1 + p_k + \cdots + p_k^{\alpha_k}) \\ &= \sigma(n') \frac{p_k^{\alpha_k+1} - 1}{p_k - 1} \end{aligned}$$

By induction hypothesis

$$\sigma(n') = \frac{p_1^{\alpha_1+1} - 1}{p_1 - 1} \cdot \frac{p_2^{\alpha_2+1} - 1}{p_2 - 1} \cdots \frac{p_{k-1}^{\alpha_{k-1}+1} - 1}{p_{k-1} - 1}$$

$$\therefore \sigma(n) = \frac{p_1^{\alpha_1+1} - 1}{p_1 - 1} \cdot \frac{p_2^{\alpha_2+1} - 1}{p_2 - 1} \cdots \frac{p_{k-1}^{\alpha_{k-1}+1} - 1}{p_{k-1} - 1} \cdot \frac{p_k^{\alpha_k+1} - 1}{p_k - 1} = \prod_{i=1}^k \frac{p_i^{\alpha_i+1} - 1}{p_i - 1}$$

■

Theorem 2.1.3. *If p is a prime and k is a positive integer, then $\phi(p^k) = p^k - p^{k-1} = p^k(1 - \frac{1}{p})$.*

Proof. The positive integers less than or equal to p^k which are not relatively prime to p^k are multiples of p , i.e., these are $p, 2p, 3p, \dots, p^{k-1}p$. Hence deleting these p^{k-1} numbers from p^k numbers: $1, 2, 3, \dots, p^k$ we obtain

$$\phi(p^k) = p^k - p^{k-1},$$

positive integers not exceeding p^k which are relatively prime to p^k .

■

Corollary 2.1.4. *If p is a prime, then $\phi(p) = p - 1$.*

Theorem 2.1.5. (Prof. Dr. Md. Fazlur Rahman [2]) The number theoretic functions τ, σ and, ϕ are multiplicative.

Theorem 2.1.6. If a and b are relatively prime positive integers, then $\phi(ab) = \phi(a)\phi(b)$.

Motivation:. Assume $(a, b) = (3, 4) = 1$, $ab = 12$ and consider the following ab numbers arranged in b rows and a columns

	$a - \text{columns}$			
$b - \text{rows}$	1	$k = 2$	3	$\rightarrow \phi(a) = 2$
	4	5	6	
	7	8	9	
	10	11	12	
	$\downarrow$ $\phi(b) = 2$			

Motivation for Theorem 2.1.6

Proof. Considering the product ab , we write the first ab integers in b rows and a columns. Thus we get

1	2	3	4	$\dots$	k	$\dots$	a
$a + 1$	$a + 2$	$a + 3$	$a + 4$	$\dots$	$a + k$	$\dots$	$2a$
$2a + 1$	$2a + 2$	$2a + 3$	$2a + 4$	$\dots$	$2a + k$	$\dots$	$3a$
$3a + 1$	$3a + 2$	$3a + 3$	$3a + 4$	$\dots$	$3a + k$	$\dots$	$4a$
$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$
$(b - 1)a + 1$	$(b - 1)a + 2$	$(b - 1)a + 3$	$(b - 1)a + 4$	$\dots$	$3(b - 1)a + k$	$\dots$	ba

Now considering the k -th column we find that if $(k, a) = 1$, then every number in k -th column is prime to a .

Now the first row contains $\phi(a)$ integers prime to a and therefore there are $\phi(a)$ columns in each of which every term is prime to a . Let k -th column be such one. Clearly this column is in A.P.(Arithmetic Progression). So, the terms of this column when divided by b will leave the remainders $0, 1, 2, \dots, (b - 1)$. Hence this column contains $\phi(b)$ terms prime to b .

Thus, there are $\phi(a)$ columns of numbers prime to a and each column contains $\phi(b)$ numbers prime to b .

Hence in the above arrangements of ab numbers there are $\phi(a)\phi(b)$ numbers which are prime to both a and b and so to the product ab . Therefore $\phi(ab) = \phi(a)\phi(b)$. So the theorem is established. ■

Corollary 2.1.7. *If $a, b, c, \dots, l$ are prime to each other, then $\phi(abc \dots l) = \phi(a)\phi(b)\phi(c) \dots \phi(l)$.*

Corollary 2.1.8. *If $p_1, p_2, p_3, \dots, p_k$ are distinct prime factors of a positive integer n , then $\phi(n) = n(1 - \frac{1}{p_1})(1 - \frac{1}{p_2})(1 - \frac{1}{p_3}) \dots (1 - \frac{1}{p_k})$.*

Corollary 2.1.9. *If $n = p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3} \dots p_k^{\alpha_k}$ where p_i 's are relatively prime in pairs, then $\phi(n) = n(1 - \frac{1}{p_1})(1 - \frac{1}{p_2})(1 - \frac{1}{p_3}) \dots (1 - \frac{1}{p_k})$.*

Example 2.1.6. Find $\phi(300)$.

Solution: $\phi(300) = \phi(3 \cdot 2^2 \cdot 5^2) = \phi(3)\phi(2^2)\phi(5^2) = 300 \cdot (1 - 1/3)(1 - 1/2)(1 - 1/5) = 300 \cdot 2/3 \cdot 1/2 \cdot 4/5 = 80$

Definition 2.1.9 (Mobius Function). *The mobius function μ is defined as*

$$\mu : \mathbb{N} \rightarrow \{-1, 0, 1\}$$

In other words,

$$\mu(n) = \begin{cases} 1 & \text{if } n = 1 \\ 0 & \text{if } n \text{ has a square factor or } a^2 \mid n \text{ for some } a \in \mathbb{Z} \\ (-1)^k & \text{if } n = p_1 p_2 \dots p_k \text{ where } p_1, p_2, \dots, p_k \text{ are distinct prime factors} \end{cases}$$

Example 2.1.7.

$$\mu(2) = (-1)^1 = -1, \quad \mu(4) = \mu(2^2) = 0, \quad \mu(6) = \mu(2 \cdot 3) = (-1)^2 = 1$$

Theorem 2.1.10 (F. Merten's Lemma). *For each integer $n \geq 1$*

$$\sum_{d \mid n} \mu(d) = \begin{cases} 1 & \text{if } n = 1 \\ 0 & \text{if } n > 1 \end{cases}$$

Proof. If $n = 1$ then by definition

$$\sum_{d \mid n} \mu(d) = \sum_{d \mid 1} \mu(d) = \mu(1) = 1.$$

If $n > 1$ then by Fundamental theorem of arithmetic 1.3.1 let

$$n = p_1^{\alpha_1} p_2^{\alpha_2} \dots p_r^{\alpha_r}$$

where p_i are distinct primes, $\alpha_i \geq 1$, $i = 1, 2, 3, \dots, r$.

$$\begin{aligned}
\therefore \sum_{d|n} \mu(d) &= \mu(1) + [\mu(p_1) + \mu(p_2) + \dots + \mu(p_r)] \\
&\quad + [\mu(p_1 p_2) + \mu(p_2 p_3) + \dots + \mu(p_{r-1} p_r)] \\
&\quad + \dots + \mu(p_1 p_2 \dots p_r) \\
&\quad + 0 + \dots + 0, \text{ (the remaining all terms vanish since they contain} \\
&\quad \text{square factors)} \\
&= \mu(1) + \sum_{i=1}^r \mu(p_i) + \sum_{\substack{i < j \\ i, j=1}}^r \mu(p_i p_j) + \dots + \mu(p_1 p_2 \dots p_r) \\
&= 1 + r(-1) + {}^r C_2 (-1)^2 + \dots + (-1)^r \\
&= 1 + {}^r C_1 (-1) + {}^r C_2 (-1)^2 + \dots + (-1)^r \\
&= (1 - 1)^r \\
&= 0 \\
\therefore \sum_{d|n} \mu(d) &= \begin{cases} 1 & \text{if } n = 1 \\ 0 & \text{if } n > 1 \end{cases}
\end{aligned}$$

■

Theorem 2.1.11. *If $(a, b) = 1$, then $\mu(ab) = \mu(a)\mu(b)$.*

Proof. If $a = b = 1$, then the proof is straightforward. If a has a square factor, then ab has a square factor, so $\mu(a) = 0$, $\mu(a)\mu(b) = 0$ and $\mu(ab) = 0$ and hence $\mu(ab) = \mu(a)\mu(b)$. Similar result holds if b has a square factor.

Now let $a = p_1 p_2 \dots p_k$ and $b = q_1 q_2 \dots q_l$. Since $(a, b) = 1$, so all the factors of a and b are distinct. Therefore $\mu(a) = (-1)^k$, $\mu(b) = (-1)^l$ and $\mu(ab) = (-1)^{k+l}$. Now $\mu(ab) = (-1)^{k+l} = (-1)^k (-1)^l = \mu(a)\mu(b)$.

Thus in all cases we have $\mu(ab) = \mu(a)\mu(b)$. ■

Note. The mobius function μ is *not completely multiplicative* since $\mu(4) = \mu(2^2) = 0$ but $\mu(2) \cdot \mu(2) = (-1)^2 = 1$.

2.2 Diophantine Equations

An equation which has more than one unknowns is called an indeterminate equation. A system of equations is called indeterminate if the number of equations is less than that of the unknowns. Indeterminate equations are called Diophantine equations, after the name of Greek mathematician Diophantus about 200 A.D., when we seek their solutions in *integers*. In this section we shall only consider the linear diophantine equations in two variables e.g., $f(x, y) = ax + by + c = 0$.

Definition 2.2.1 (Diophantine Equations). *Let $a, b, c \in \mathbb{Z}$ with $ab \neq 0$. Then any linear equation of the form $ax + by = c$, where the values of x and y are restricted to the set of integers $\mathbb{Z}$, is called the linear diophantine equation.*

The following theorem gives the information when the linear diophantine equation has solution or not.

Theorem 2.2.1. *The linear diophantine equation $ax + by = c$ has a solution if and only if $d \mid c$ where $d = (a, b)$.*

Proof. First suppose that $ax + by = c \cdots (1)$ has a solution (x_0, y_0) . Then $ax_0 + by_0 = c \cdots (2)$ Since $(a, b) = d$, so $ax_0 + by_0$ is a multiple of d . Therefore $ax_0 + by_0 = rd$, (say) $\cdots (3)$ where $r \in \mathbb{Z}$. From (2) and (3) we have

$$c = td \Rightarrow d \mid c.$$

Conversely, suppose that $d \mid c$. Then $c = td$ where $t \in \mathbb{Z} \cdots (4)$. Also $(a, b) = d$ gives $d = au + bv$, for some $u, v \in \mathbb{Z} \Rightarrow td = atu + btv \cdots (5)$. From (4) and (5) we have $c = atu + btv \Rightarrow a(tu) + b(tv) = c$. Comparing this with the given equation $ax + by = c$ we have $x = tu, y = tv$ is a solution. ■

Theorem 2.2.2. *If (x_0, y_0) is a particular solution of the linear diophantine equation $ax + by = c$ then any other solution (*general solution*) of the equation is*

$$x = x_0 + \frac{b}{d}t, \quad y = y_0 - \frac{a}{d}t,$$

where $t \in \mathbb{Z}$ and $d := (a, b) \mid c$.

Proof. We first show that the expressions $x = x_0 + \frac{b}{d}t$, $y = y_0 - \frac{a}{d}t$ represent solutions of the linear diophantine equation $ax + by = c$ $\cdots$ (1). Substituting the values of x and y in (1), we get

$$a\left(x_0 + \frac{b}{d}\right)t + b\left(y_0 - \frac{a}{d}\right)t = c$$

$$ax_0 + by_0 = c$$

Since (x_0, y_0) is a particular solution of the linear diophantine equation $ax + by = c$, the equation $ax + by = c$ is satisfied by

$$x = x_0 + \frac{b}{d}t, \quad y = y_0 - \frac{a}{d}t,$$

where $t \in \mathbb{Z}$.

Now since (x, y) and (x_0, y_0) are solutions of $ax + by = c$, so $ax + by = c$ and $ax_0 + by_0 = c$. Therefore

$$ax + by = ax_0 + by_0$$

$$a(x - x_0) = b(y_0 - y)$$

$$\frac{a}{d}(x - x_0) = \frac{b}{d}(y_0 - y)$$

So $\frac{b}{d} \mid x - x_0$ and $\frac{a}{d} \mid y_0 - y$ as $\left(\frac{a}{d}, \frac{b}{d}\right) = 1$. It follows that $x - x_0 = \frac{b}{d}t$, $y_0 - y = \frac{a}{d}t$ and hence

$$x = x_0 + \frac{b}{d}t, \quad y = y_0 - \frac{a}{d}t,$$

where $t \in \mathbb{Z}$. ■

Corollary 2.2.3. *If $(a, b) = 1$ and (x_0, y_0) is a particular solution of the linear diophantine equation $ax + by = c$, then its general solutions are given by $x = x_0 + bt$, $y = y_0 - at$ where $t \in \mathbb{Z}$.*

Example 2.2.1. *Find the positive integral solutions of the linear diophantine equation $172x + 20y = 1000$.*

Solution: Here $a = 172$, $b = 20$, $c = 1000$, and $d := (a, b) = (172, 20) = 4$ obtained by the following Euclidean algorithm:

$$172 = 20 \cdot 8 + 12$$

$$20 = 12 \cdot 1 + 8$$

$$12 = 8 \cdot 1 + 4$$

$$8 = 4 \cdot 2 + 0$$

Since $d \mid c$, a solution to the equation $172x + 20y = 1000$ exists by [Theorem 2.2.1](#).

Using steps of Euclid's algorithm from backward direction $d = 4$ can be expressed as a linear combination of $a = 172$ and $b = 20$.

$$\begin{aligned}
4 &= 12 + (-1) \cdot 8 \\
&= 12 + (-1) \cdot \{20 + (-1) \cdot 12\} \\
&= 2 \cdot 12 + (-1) \cdot 20 \\
&= 2 \cdot \{172 + (-8) \cdot 20\} + (-1) \cdot 20 \\
&= 172 \cdot (2) + 20 \cdot (-17) \\
\therefore 172 \cdot (500) + 20 \cdot (-4250) &= 1000
\end{aligned}$$

It follows that $(x_0, y_0) = (500, -4250)$ is a particular solution to the equation $172x + 20y = 1000$. Hence the general solutions given by *Theorem 2.2.2* are:

$$x = x_0 + \frac{b}{d}t, \quad y = y_0 - \frac{a}{d}t, \quad \text{with } t \in \mathbb{Z}.$$

That is, $x = 500 + 5t, \quad y = -4250 - 43t \quad \dots (1)$

Now the positive integral solutions can be obtained by considering the system of inequalities

$$\begin{aligned}
4x = 500 + 5t &> 0 \text{ and } y = -4250 - 43t > 0 \\
\Rightarrow t &> -\frac{500}{5} = -100 \text{ and } t < -\frac{4250}{43} = -98\frac{36}{43} \\
\Rightarrow -100 &< t < -98\frac{36}{43}
\end{aligned}$$

Since t is an integer so $t = -99$. Hence from (1)

$$x = 500 + 5(-99) = 5 \text{ and } y = -4250 - 43(-99) = 7$$

Therefore $(x, y) = (5, 7)$ is the only positive solution of the linear diophantine equation $172x + 20y = 1000$.

1. Evaluate $\sigma(\tau(\phi(7)))$. [Ans:7]
2. Calculate the value of Euler ϕ function at 30, 50, 100, 120, 240, and 264.
3. The number theoretic functions τ and σ are multiplicative.
4. Find the positive integral solutions of the linear diophantine equation $18x+5y = 48$.
5. Determine the particular solution of the linear diophantine equation $39x + 26y = 105$.
6. A man presented a check for Taka 510 to a bank and wished to be paid in 20 and 50 taka notes. In how many ways and means can the cashier meet his request.
- 7.

Chapter 3

Congruences

3.1 Congruences and Its Properties

The concept of congruences was introduced by Carl Friedrich Gauss about 1800, one of the greatest mathematician of all time. Congruence often arises in every day life. For instance, if the second of January is Sunday, then 9,16,23 of the same month are all Sundays, since when they are divided by 7, the remainders are all 2.

A congruence is nothing but a refined statement about divisibility. Congruence can be treated in the same manner as equations. Let m be a positive integer. Two integers a and b leave remainders when divided by m . If the remainders are same we say that a is congruent to b modulo m , and we write

$$a \equiv b(\text{mod } m) \quad \text{or} \quad m \mid a - b.$$

Alternatively,

Definition 3.1.1 (Congruence). *If the difference of two integers a and b is divisible by m , we shall say that a is congruent to b modulo m , and we write*

$$a \equiv b(\text{mod } m) \quad \text{or} \quad m \mid a - b.$$

Definition 3.1.2 (Incongruence). *If the difference of two integers a and b is not divisible by m , we shall say that a is incongruent to b modulo m , and we write*

$$a \not\equiv b(\text{mod } m) \quad \text{or} \quad m \nmid a - b.$$

Example 3.1.1. $7 \equiv 3(\text{mod } 2)$, $9 \not\equiv 4(\text{mod } 3)$, and $13 \equiv 3(\text{mod } 5)$.

Theorem 3.1.1. *If $a \equiv b(\text{mod } m)$ and $c \equiv d(\text{mod } m)$, then*

$$(i) \ a + c \equiv b + d \pmod{m}$$

$$(ii) \ a - c \equiv b - d \pmod{m}$$

$$(iii) \ ac \equiv bd \pmod{m}$$

Proof. Here $a - b$ and $c - d$ are both multiples of m , say $a - b = t_1m$ and $c - d = t_2m$.

$$(i) \ (a - b) + (c - d) = (a + c) - (b + d) = (t_1 + t_2)m = t_3m, \text{ say. So, } a + c \equiv b + d \pmod{m}.$$

$$(ii) \ (a - c) - (b - d) = (a - b) - (c - d) = (t_1 - t_2)m = t_4m, \text{ say. So, } a - c \equiv b - d \pmod{m}.$$

$$(iii) \ a - b = t_1m \Rightarrow (a - b)c = t_1mc \text{ where } t_5 = t_1c. \text{ So, } ac - bc = t_5m \cdots (A)$$

$$c - d = t_2m \Rightarrow (c - d)b = t_2mb \text{ where } t_6 = t_2b. \text{ So, } bc - bd = t_6m \cdots (B) \text{ Then}$$

$$\text{from (A) and (B), } ac - bc + bc - bd = (t_5 + t_6)m \Rightarrow ac - bd = t_7m, \text{ say. So,}$$

$$ac \equiv bd \pmod{m}.$$

■

Theorem 3.1.2 (**transitive law**). If $a \equiv b \pmod{m}$ and $b \equiv c \pmod{m}$, then $a \equiv c \pmod{m}$

Theorem 3.1.3. $a \equiv b \pmod{m} \Rightarrow na \equiv nb \pmod{m}$, but the converse need not hold.

$$\text{e.g., } 4 \cdot 7 \equiv 4 \cdot 2 \pmod{10} \Rightarrow 7 \not\equiv 2 \pmod{10} \text{ but } 7 \equiv 2 \pmod{5}.$$

Theorem 3.1.4 (**Cancellation law**). If $na \equiv nb \pmod{m}$ and $(n, m) = g$, then $a \equiv b \pmod{\frac{m}{g}}$

Proof. Since $(n, m) = g$, we have $n = gN$ and $m = gM$ where $(M, N) = 1$. Given that $m \mid n(a - b) \Rightarrow gM \mid gN(a - b) \Rightarrow M \mid N(a - b) \Rightarrow M \mid a - b$ Therefore, $a \equiv b \pmod{M}$ and hence $a \equiv b \pmod{\frac{m}{g}}$. ■

Corollary 3.1.5. If a, b, g are integers such that $na \equiv nb \pmod{m}$ and $(m, n) = 1$, then $a \equiv b \pmod{m}$.

Definition 3.1.3. Let $a, b (b > 0)$ be any two integers. Then $\exists$ integers q, r such that $a = bq + r$ where $0 \leq r < b$. Then r is called the least residue of a modulo m .

Here $r := 0, 1, 2, \dots, b - 1$ form a complete set of least residues modulo b .

$r, a + r, 2a + r, 3a + r, 4a + r$ are

$1, 4, 2, 0, 3$ respectively.

Motivation:. Let $r = 6$ be any integer, $a = 3$, $b = 5$, and $(a, b) = 1$. Then the least residues modulo b of

Theorem 3.1.6 (Least Residue Theorem). If a and $b(b > 0)$ are relatively prime and if r is any integer, then the least residues modulo b of

$$r, a + r, 2a + r, 3a + r, \dots, (b - 1)a + r \cdots (1)$$

are

$$0, 1, 2, 3, \dots, (b - 1) \cdots (2)$$

in some rearranged order.

Proof. By definition, the least residue modulo b of any integer is one of the numbers (2). There are b numbers (1) and b numbers (2). The theorem will be established if we can show that no two of the numbers (1) have the same least residue (2). Any two of the numbers of (1) may be denoted by

$$sa + r, 0 \leq s < b \text{ and } ta + r, 0 \leq t < b \text{ with } s > t.$$

If they have the same least residue modulo b , they are congruent. Then

$$sa + r \equiv ta + r \pmod{b}$$

$$sa \equiv ta \pmod{b}$$

$$s \equiv t \pmod{b}, \text{ since } (a, b) = 1$$

But $s - t$ is positive and less than b so that it is not divisible by b . This contradiction shows that no two distinct numbers (1) have the same least residue modulo b . Hence the theorem is proved. ■

Corollary 3.1.7. If $(a, b) = 1$, then $a, 2a, 3a, \dots, (b - 1)a$ are congruent modulo b to $1, 2, 3, \dots, (b - 1)$ in some order.

Proof. Since $(a, b) = 1$, no one of ia is divisible by b ; $i := 1, 2, 3, \dots, b - 1$. So, no residue is zero. Thus, the corollary is established. ■

3.2 Fermat's Theorem, Euler's Theorem and Wilson's Theorem

Theorem 3.2.1 (Fermat's Theorem). *If p is a prime and $(a, p) = 1$, then $a^{p-1} \equiv 1 \pmod{p}$.*

This theorem was conjectured by Fermat and was first proven by Euler in 1736. It is also called **Fermat's little theorem**.

Proof. By the least residue theorem the integers $a, 2a, 3a, \dots, (p-1)a$ are congruent modulo p to $1, 2, 3, \dots, p-1$ in some order. The product of the first set is congruent to that of the second set. Then

$$a^{p-1} 1 \cdot 2 \cdot 3 \cdot \dots \cdot p-1 \equiv 1 \cdot 2 \cdot 3 \cdot \dots \cdot p-1 \pmod{p}$$

$$a^{p-1} (p-1)! \equiv (p-1)! \pmod{p}$$

$$a^{p-1} \equiv 1 \pmod{p}, \text{ since } ((p-1)!, p) = 1$$

Hence the theorem is proved. ■

Corollary 3.2.2. *If p is a prime and a is any integer, then $a^p \equiv a \pmod{p}$.*

Note. *The converse of the Fermat's theorem is not true, i.e. if $a^{p-1} \equiv 1 \pmod{p}$, p need not be prime.*

Motivation:. *The positive integers not exceeding $m = 8$ and relatively prime to $m = 8$ are $a := 1, 3, 5$, and 7 . Now construct the following congruences with $a = 3$:*

$$3 \cdot 1 \equiv 3, \quad 3 \cdot 3 \equiv 1, \quad 3 \cdot 5 \equiv 7, \quad 3 \cdot 7 \equiv 5 \pmod{m}$$

After multiplying we get:

$$\begin{aligned} 3^4 \cdot 1 \cdot 3 \cdot 5 \cdot 7 &\equiv 3 \cdot 1 \cdot 7 \cdot 5 \pmod{m} \\ \Rightarrow 3^4 &\equiv 1 \pmod{m}, \text{ since } (1 \cdot 3 \cdot 5 \cdot 7, m) = 1 \\ \therefore 3^{\phi(8)} &\equiv 1 \pmod{m} \\ \Rightarrow a^{\phi(m)} &\equiv 1 \pmod{m} \text{ where } (a, m) = 1. \end{aligned}$$

This result is known as the Euler's theorem.

Theorem 3.2.3 (Euler's Theorem). *If m be any positive integer and a be any integer prime to m , i.e. $(a, m) = 1$, then $a^{\phi(m)} \equiv 1 \pmod{m}$.*

Proof. Let $a_1, a_2, a_3, \dots, a_{\phi(m)}$ be the positive integers, in ascending order, less than m and prime to m . Now consider the products $aa_1, aa_2, aa_3, \dots, aa_{\phi(m)}$. Since $(a, m) = 1$,

it follows that $aa_1, aa_2, aa_3, \dots, aa_{\phi(m)}$ are congruent modulo m , not necessarily in order of appearance to $a_1, a_2, a_3, \dots, a_{\phi(m)}$.

Then

$$\begin{aligned} aa_1 &\equiv a'_1 \pmod{m} \\ aa_2 &\equiv a'_2 \pmod{m} \\ aa_3 &\equiv a'_3 \pmod{m} \\ &\dots \quad \dots \quad \dots \\ aa_{\phi(m)} &\equiv a'_{\phi(m)} \pmod{m} \end{aligned}$$

where $a'_1, a'_2, a'_3, \dots, a'_{\phi(m)}$ are the integers $a_1, a_2, a_3, \dots, a_{\phi(m)}$ in some order.

On taking the product of these $\phi(m)$ congruences, we get

$$\begin{aligned} aa_1 \cdot aa_2 \cdot aa_3 \cdot \dots \cdot aa_{\phi(m)} &\equiv a'_1 \cdot a'_2 \cdot a'_3 \cdot \dots \cdot a'_{\phi(m)} \pmod{m} \\ &\equiv a_1 \cdot a_2 \cdot a_3 \cdot \dots \cdot a_{\phi(m)} \pmod{m} \\ \Rightarrow a^{\phi(m)} (a_1 a_2 a_3 \cdot \dots \cdot a_{\phi(m)}) &\equiv a_1 a_2 a_3 \cdot \dots \cdot a_{\phi(m)} \pmod{m} \end{aligned}$$

Since $(a_i, m) = 1$ for each i , we have $(a_1 a_2 a_3 \cdot \dots \cdot a_{\phi(m)}, m) = 1$ and hence by the Cancellation law (Theorem 3.1.4) $a^{\phi(m)} \equiv 1 \pmod{m}$. ■

Corollary 3.2.4. *Deduce Fermat's theorem from Euler's theorem.*

Proof. Since $(a, p) = 1$, by Euler's theorem $a^{\phi(p)} \equiv 1 \pmod{p}$. But if p is a prime, then $\phi(p) = p - 1$. Hence $a^{p-1} \equiv 1 \pmod{p}$. ■

Motivation:. If $p = 11$, each of the product of $\frac{p-3}{2}$ pairs, namely $2 \cdot 6, 3 \cdot 4, 5 \cdot 9, 7 \cdot 8 \equiv 1 \pmod{11}$. Then $10! = 1 \cdot 2 \cdot 3 \cdot 4 \cdot 5 \cdot 6 \cdot 7 \cdot 8 \cdot 9 \cdot 10 = (1 \cdot 10)(2 \cdot 6)(3 \cdot 4)(5 \cdot 9)(7 \cdot 8) \equiv 10 \pmod{11} \equiv -1 \pmod{11} \Rightarrow (p-1)! \equiv -1 \pmod{p}$.

Theorem 3.2.5 (Wilson's Theorem). *If p is a prime, then $(p-1)! \equiv -1 \pmod{p}$.*

Proof. Let a denote any one of the numbers $1, 2, 3, \dots, p-1$. Clearly $(a, p) = 1$, since p is a prime. Then by the corollary of the least residue theorem 3.1.7 the integers

$$a, 2a, 3a, \dots, (p-1)a \quad \dots (1)$$

are congruent modulo p to

$$1, 2, 3, \dots, p-1 \quad \dots (2)$$

in some order. Hence there exists one and only one number in (1), say ka which will be congruent to 1 with modulo p , i.e.,

$$ka \equiv 1 \pmod{p} \quad \dots (3).$$

If $k = a$ then from (3) we have $p \mid a^2 - 1$, i.e., $p \mid a - 1$ or $p \mid a + 1$. Since p is prime and $a < p$, it follows that either $a + 1 = p$ or $a - 1 = 0 \Rightarrow a = 1, p - 1$

For all other values of a , k differ from a . This means that for every a belonging to the $p - 3$ numbers

$$2, 3, \dots, p - 2 \quad \dots (4)$$

there exists one and only one number k also belonging to (4) but different from a such that

$$ka \equiv ak \equiv 1 \pmod{p}.$$

Thus, the numbers in (4) can be arranged into $\frac{p-3}{2}$ pairs such that the product of the integers of each pair is congruent to 1(mod p). Taking product of all these pairs we obtain

$$\begin{aligned} 2 \cdot 3 \cdot \dots \cdot p - 2 &\equiv 1 \pmod{p} \\ \Rightarrow 1 \cdot 2 \cdot 3 \cdot \dots \cdot (p - 2) \cdot (p - 1) &\equiv (p - 1) \pmod{p} \\ \Rightarrow (p - 1)! &\equiv 1 \pmod{p} \end{aligned}$$

■

Proof. [**Alternative**] Let p be a prime and $(x, p) = 1$. Then by Fermat's theorem we have $x^{p-1} - 1 \equiv 0 \pmod{p}$. This equation has $p - 1$ roots with modulo p and the roots are

$$1, 2, 3, \dots, p - 1$$

$\therefore x^{p-1} - 1 \equiv (x - 1)(x - 2)(x - 3) \cdot \dots \{x - (p - 1)\} \pmod{p}$. This congruent relation is satisfied for all values of x . Letting $x = 0$ we have:

$$\begin{aligned} -1 &\equiv (-1)(-2)(-3) \cdot \dots \{-(p - 1)\} \pmod{p} \\ (-1)^{p-1}(p - 1)! &\equiv -1 \pmod{p} \quad \dots (1) \end{aligned}$$

Since p is a prime, so either $p = 2$ or p is an odd prime.

Case-I: If $p = 2$ then (1) implies that

$$-(2 - 1)! \equiv -1(\text{mod } 2)$$

$$-1 \equiv -1(\text{mod } 2)$$

$$-1 + 2 \equiv -1(\text{mod } 2)$$

$$(2 - 1)! \equiv -1(\text{mod } 2)$$

$$(p - 1)! \equiv -1(\text{mod } p)$$

Case-I: If p is an odd prime, then $(-1)^{p-1} = 1$ and hence (1) yields that $(p - 1)! \equiv -1(\text{mod } p)$. ■

Theorem 3.2.6 (**Converse of Wilson's Theorem**). *If $(p - 1)! \equiv -1(\text{mod } p)$, then p is a prime.*

Proof. Suppose that p is not a prime. Then p is composite and so there exist a divisor d where $1 < d < p$. Furthermore since d is a factor of $1 \cdot 2 \cdot 3 \cdots (p - 2) \cdot (p - 1)$, so we can write

$$(p - 1)! \equiv 0(\text{mod } d)$$

$$(p - 1)! \not\equiv -1(\text{mod } d)$$

$$(p - 1)! \not\equiv -1(\text{mod } p)$$

This is a contradiction to the converse statement. It follows that p must be a prime. ■

1. Congruence is an equivalence relation.

Chapter 4

Solutions of Congruences

4.1 Linear Congruences

Definition 4.1.1 (**Polynomial congruence**). If $m \nmid a_n$ i.e., $(a_n, m) = 1$ then the congruence $a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0 \equiv 0 \pmod{m}$ is said to be a polynomial congruence of degree n where a 's are restricted to the integers.

Definition 4.1.2 (**Linear congruence**). If $m \nmid a$ i.e., $(a, m) = 1$ then the congruence $ax \equiv b \pmod{m}$ is said to be a linear congruence where $a, b \in \mathbb{Z}$.

Theorem 4.1.1. The linear congruence $ax \equiv b \pmod{m}$ has a **unique** solution if $(a, m) = 1$.

Proof. Given $(a, m) = 1$ and $ax \equiv b \pmod{m} \quad \cdots (1)$

Therefore

$$\begin{aligned} a^{\phi(n)-1} ax &\equiv a^{\phi(n)-1} b \pmod{m} && \text{(multiplying (1) by } a^{\phi(n)-1}) \\ \Rightarrow a^{\phi(n)} x &\equiv ba^{\phi(n)-1} \pmod{m} && \cdots (2) \\ \text{But } a^{\phi(n)} &\equiv 1 \pmod{m} && \text{(Euler's theorem)} \\ \Rightarrow x &\equiv a^{\phi(n)} x \pmod{m} && \text{(multiplying both sides by } x) \\ \Rightarrow x &\equiv ba^{\phi(n)-1} \pmod{m} && \text{(using transitive law 3.1.2 on (2))} \end{aligned}$$

which is the required solution of the linear congruence $ax \equiv b \pmod{m}$.

Uniqueness: Let x_1 and x_2 be two solutions of the linear congruence (1). Then

$$\begin{aligned}
ax_1 &\equiv b \pmod{m} \text{ and } ax_2 \equiv b \pmod{m} \\
\therefore ax_1 - ax_2 &\equiv 0 \pmod{m} \\
\Rightarrow a(x_1 - x_2) &\equiv 0 \pmod{m} \\
\Rightarrow x_1 - x_2 &\equiv 0 \pmod{m} \quad \text{since } (a, m) = 1 \\
\Rightarrow x_1 &\equiv x_2 \pmod{m}
\end{aligned}$$

Thus, the solution is unique. ■

Theorem 4.1.2. *If $(a, m) = g$, $g > 1$ then the congruence $ax \equiv b \pmod{m}$ has*

- (i) *no root if $g \nmid b$*
- (ii) *exactly g incongruent roots if $g \mid b$. The roots are $x_0, x_0 + \frac{m}{g}, x_0 + 2 \cdot \frac{m}{g}, \dots, x_0 + (g-1) \cdot \frac{m}{g}$ where x_0 is the unique root of $\frac{a}{g}x \equiv \frac{b}{g} \pmod{\frac{m}{g}}$.*

Proof. Given $(a, m) = g$, $g > 1$

$\therefore a = gA$, $m = gM$, where $(A, M) = 1$ for some $A, M \in \mathbb{Z}$

- (i) Now $ax \equiv b \pmod{m} \Rightarrow m \mid (ax - b) \Rightarrow gM \mid (gAx - b)$. This will be possible only if b has a factor g i.e., $b = gB$ for some $B \in \mathbb{Z} \Rightarrow g \mid b$. Thus, if $g \nmid b$ then $ax \equiv b \pmod{m}$ has no root.

- (ii) If $g \mid b \Rightarrow b = gB$ for some $B \in \mathbb{Z}$. Again

$$\begin{aligned}
ax &\equiv b \pmod{m} \\
\Rightarrow gAx &\equiv gB \pmod{gM} \\
\Rightarrow Ax &\equiv B \pmod{M} \quad \dots (1) \text{ which has a unique solution, say } x_0, \text{ by (i) since } (A, M) = 1 \\
\Rightarrow M &\mid (Ax - B) \\
\Rightarrow gM &\mid g(Ax_0 - B), \quad \text{since } x = x_0 \text{ is a solution to (1)} \\
\Rightarrow m &\mid (ax_0 - b) \\
\Rightarrow ax_0 &\equiv b \pmod{m} \quad \dots (2) \\
\therefore x_0 &\text{ is a solution of the given congruence.}
\end{aligned}$$

Suppose x' is any other solution of $ax \equiv b(\text{mod } m)$. Then $ax' \equiv b(\text{mod } m) \cdots (3)$

Applying symmetric relation¹ on (2) we obtain $b \equiv ax_0(\text{mod } m) \cdots (4)$.

Now using transitive relation on (3) and (4) we get

$$\begin{aligned}
 ax' &\equiv ax_0(\text{mod } m) \cdots (5) \\
 \Rightarrow m &\mid (ax' - ax_0) \\
 \Rightarrow gM &\mid gA(x' - x_0) \\
 \Rightarrow M &\mid A(x' - x_0) \\
 \Rightarrow M &\mid (x' - x_0), \quad \text{since } (A, M) = 1 \\
 \Rightarrow x' - x_0 &= Mk, \quad \text{for some } k \in \mathbb{Z}
 \end{aligned}$$

But division algorithm $\Rightarrow k = gq + r, 0 \leq r < g, q \in \mathbb{Z}$

$$\begin{aligned}
 \text{So } x' &= x_0 + M(gq + r) = x_0 + gMq + Mr \\
 \Rightarrow x' &= x_0 + mq + \frac{m}{g}r \\
 \Rightarrow x' &\equiv x_0 + \frac{m}{g}r(\text{mod } m)
 \end{aligned}$$

Thus, if $ax \equiv b(\text{mod } m)$ admits a solution x_0 , then it has g incongruent solutions, namely:

$$x_0, x_0 + \frac{m}{g}, x_0 + 2 \cdot \frac{m}{g}, \dots, x_0 + (g-1) \cdot \frac{m}{g}.$$

■

Example 4.1.1. Solve $35x \equiv 4(\text{mod } 9)$

Solution: Here $(35, 9) = 1$. Therefore the given linear congruence has a unique solution.

$$\text{So } \left\{ \begin{array}{l} 35x \equiv 4(\text{mod } 9) \\ \Rightarrow 36x - x \equiv 4(\text{mod } 9) \\ \Rightarrow -x \equiv 4(\text{mod } 9), \quad \text{by Theorem 3.1.1} \\ \Rightarrow x \equiv -4(\text{mod } 9) \\ \Rightarrow x \equiv -4(\text{mod } 9), \quad \text{by Theorem 3.1.3} \\ \Rightarrow x \equiv -9 + 5(\text{mod } 9) \\ \Rightarrow x \equiv 5(\text{mod } 9) \\ \therefore x = 5 \text{ is the solution of the given congruence} \end{array} \right.$$

¹If $a \equiv b(\text{mod } m)$ then $b \equiv a(\text{mod } m)$

Example 4.1.2. Solve $18x \equiv 30 \pmod{42}$

Solution: Here $a = 18, b = 30, m = 42, g = (18, 42) = 6$ and $g \mid b$. Therefore the given congruence has exactly 6 solution. Now

$$\begin{aligned} 18x &\equiv 30 \pmod{42} \\ \Rightarrow \frac{18}{6}x &\equiv \frac{30}{6} \pmod{\frac{42}{6}} \\ \Rightarrow 3x &\equiv 5 \pmod{7} \quad \dots (1) \\ \Rightarrow 15x &\equiv 25 \pmod{7} \\ \Rightarrow x &\equiv 4 \pmod{7} \\ \therefore x = x_0 = 4 &\text{ is a particular solution to the linear congruence (1)} \end{aligned}$$

Hence the 6 roots of the given congruence $18x \equiv 30 \pmod{42}$ are: $x = x_0 + i \cdot \frac{m}{g}$, $i = 1, 2, 3, 4, 5$ i.e., 4, 11, 18, 25, 32, and 39.

1. Congruence is an equivalence relation.

Chapter 5

Quadratic Residuacity

5.1 Quadratic Residue and Nonresidues

Definition 5.1.1 (**Quadratic residue and Quadratic nonresidue**). Let $p > 2$ and $p \nmid a$, then a is called quadratic residue modulo p , often denoted by aRp , if $x^2 \equiv a \pmod{p}$ is solvable. In other words, a is called quadratic nonresidue modulo p and is often denoted by aNp .

Example 5.1.1. Quadratic residue modulo 11 are 1, 3, 4, 5, and 9 because $1 = 1^2$, $3 = 5^2$, $4 = 2^2$, $5 = 4^2$, $9 = 3^2$

Quadratic nonresidue modulo 11 are: 2, 6, 7, 8, 10 because none of the quadratic congruences $2 \equiv x^2 \pmod{11}$, $6 \equiv x^2 \pmod{11}$, $7 \equiv x^2 \pmod{11}$, $8 \equiv x^2 \pmod{11}$, $10 \equiv x^2 \pmod{11}$

5.2 Legendre Symbol

Definition 5.2.1 (**Legendre Symbol**). If $p > 2$ and $(a, p) = 1$, then the Legendre symbol is defined by

$$\left(\frac{a}{p}\right) = \begin{cases} +1 & \text{if } a \text{ is a quadratic residue modulo } p \\ -1 & \text{if } a \text{ is a quadratic nonresidue modulo } p \end{cases}$$

Example 5.2.1. Solution:

1. Congruence is an equivalence relation.

Chapter 6

Sets, The Real Number System, and Functions

6.1 Sets

Definition 6.1.1 (Set). *A set is a well-defined list, collection, or class of objects.*

Examples include the following:

Example 6.1.1. (a) $A = \{1, 5, 8, 10\}$

(b) $B = \{2n : n \in N\}$

Does **EVERY** collection of objects make up a set?

The set operations are binary operations and are some useful tools to obtain new sets from the old ones through combining(**union**), intersecting(**intersection**), and taking differences(**difference or complement**).

Definition 6.1.2 (Union of two sets). *The union of two sets A and B is mathematically defined as*

$$A \cup B = \{x : x \in A \text{ or } x \in B \text{ or } x \in \text{both}\}.$$

Definition 6.1.3 (Intersection of two sets). *The intersection of two sets A and B is mathematically defined as*

$$A \cap B = \{x : x \in A, x \in B\}.$$

Definition 6.1.4 (Difference of two sets). *The difference of two sets A and B is mathematically defined as*

$$A \sim B = \{x \in A : x \notin B\}.$$

The difference of A and B is often termed as **the complement of B relative to A**

Definition 6.1.5 (Venn diagram). *Venn diagram is a convenient way to depict the relations among the sets.*

6.1.1 Cartesian Product Sets and their visualization

Definition 6.1.6 (Cartesian Product set). *The cartesian product of two nonvoid sets A and B is mathematically defined as*

$$A \times B = \{(a, b) : a \in A, b \in B\}.$$

Problem 6.1.1. *Visualize $A \times B$ where $A = \{x : 1 \leq x \leq 2\}$ and $B = \{x : 0 \leq x \leq 1 \text{ or } 2 \leq x \leq 3\}$.*

6.2 The Real Number System

6.2.1 The Field Properties and the Order Properties of $\mathbb{R}$

The real number system $\mathbb{R}$ can be described as a complete ordered field.

- The field properties of $\mathbb{R}$, often called the algebraic properties, are based on the two operations of addition and multiplication.
- The order properties of $\mathbb{R}$ are based on inequalities of numbers.
- The completeness properties of $\mathbb{R}$ are based on some completeness axioms which will be discussed later.

The historical development of real number system $\mathbb{R}$ was from the positive integers, called the natural numbers $\mathbb{N}$ to the rational numbers $\mathbb{Q}$ to the full real numbers $\mathbb{R} := \mathbb{Q} \cup \mathbb{Q}'$, where the irrational numbers $\mathbb{Q}'$ were obtained either as cuts of rationals (Dedekind), or as Cauchy sequences or as suprema of sets of rationals (Supremum property of $\mathbb{R}$). The existence of irrationals is guaranteed by any of the three theorems called the Completeness Axiom of $\mathbb{R}$.

Definition 6.2.1 (Field Properties of $\mathbb{R}$). *On the set of real numbers there are two binary operations, denoted by $+$ and $\cdot$ and called addition and multiplication, respectively. These operations satisfy the following properties:*

- (A1) closure property of addition
- (A2) commutative property of addition
- (A3) associative property of addition
- (A4) existence of an additive identity, called zero element, in $\mathbb{R}$

(A5) existence of an additive inverse, called negative element, in $\mathbb{R}$

(M1) closure property of multiplication

(M2) commutative property of multiplication

(M3) associative property of multiplication

(M4) existence of a multiplicative identity, called unit element, in $\mathbb{R}$

(M5) existence of a multiplicative inverse, called reciprocals, in $\mathbb{R}$

(D) distributive property of multiplication over addition

The real number system $\mathbb{R}$ is a **FIELD** because it obeys the field axioms.

Definition 6.2.2 (Order Properties of $\mathbb{R}$). On the field of real numbers there is a binary relation denoted by $<$. For all $x, y, z \in \mathbb{R}$ this relation satisfies the following properties:

(O1) Law of Trichotomy: either $x < y$ or $x = y$ or $y < x$

(O2) Transitive Law: $x < y$ and $y < z$ implies $x < z$

(O3) compatibility of $<$ and $+$: $x < y$ implies $x + z < y + z$

(O4) compatibility of $<$ and $\cdot$: $0 < z$ and $x < y$ implies $x \cdot z < y \cdot z$

The real number system $\mathbb{R}$ is an **ORDERED FIELD** because it obeys the order axioms.

6.2.2 The Completeness Properties of $\mathbb{R}$

Theorem 6.2.1. $\sqrt{2}$ is not a rational number.

Proof. If $\sqrt{2}$ be a rational number, assume $\sqrt{2} = \frac{m}{n}$ where $(m, n) = 1$ and $m, n \in \mathbb{Z}, n \neq 0 \implies m^2 = 2n^2 \implies m$ is an even integer, so $m = 2k$, say. So $(2k)^2 = 2n^2 \implies n^2 = 2k^2 \implies n$ is an even integer, a contradiction to the assumption. Hence $\sqrt{2}$ is not a rational number. ■

Definition 6.2.3 (Intervals). Open interval: $(a, b) = \{x \in \mathbb{R} : a < x < b\}$ and closed interval: $[a, b] = \{x \in \mathbb{R} : a \leq x \leq b\}$.

Definition 6.2.4 (Bounded Set). Let $S \subset \mathbb{R}$. Then $u \in \mathbb{R}$ is said to be an upper bound of S if $s \leq u$ for all $s \in S$ and $l \in \mathbb{R}$ is said to be a lower bound of S if $l \leq s$ for all $s \in S$. Set S is bounded above if it has an upper bound and bounded below if it has a lower bound. It is said to be *bounded* if it has both upper bound and lower bound. It is unbounded if it lacks either an upper bound or a lower bound.

Definition 6.2.5 (Suprema and Infima). If S is bounded above, then an upper bound $u \in \mathbb{R}$ is said to be a least upper bound (lub) or *supremum* of S if no number smaller than u is an upper bound of S . Similarly greatest lower bound (glb) or *infimum* is defined.

Theorem 6.2.2. An upper bound u of a nonempty set $S \subseteq \mathbb{R}$ is the supremum of S if and only if for each $\epsilon > 0$ there exists an $s_\epsilon \in S$ such that $u - \epsilon < s_\epsilon$.

Example 6.2.1. • If $S = (0, 1)$, the $\sup S = 1$, and $\inf S = 0$.

- If $S = [0, 2]$ the $\sup S = 2$, greatest element of S and $\inf S = 0$, the least element of S .
- If $S = \{\frac{1}{n} : n \in \mathbb{N}\}$, the $\sup S = 1$, greatest element of S and $\inf S = 0$. But the set has no least element.

Example 6.2.2. Since every real number is an upper bound for the empty set, so the empty set has no supremum. Similarly it has no infimum.

Theorem 6.2.3 (Completeness Axiom of $\mathbb{R}$ /The Supremum Property of $\mathbb{R}$). Every nonempty set of real numbers that has an upper bound has a supremum in $\mathbb{R}$.

Theorem 6.2.4 (Completeness Axiom of $\mathbb{R}$ /The Infimum Property of $\mathbb{R}$). Every nonempty set of real numbers that has a lower bound has an infimum in $\mathbb{R}$.

Theorem 6.2.5. There exists a positive real number x such that $x^2 = 2$.

Proof. Let $S = \{s \in \mathbb{R} : 0 \leq s, s^2 < 2\}$. Since $1 \in S$, the set is not empty. Also, S is bounded above by 2, because if $t > 2$, then $t^2 > 4$ so that $t \notin S$. Therefore the Supremum Property implies that the set S has a supremum in $\mathbb{R}$ and let $x = \sup S$ (here $\sup S = \sqrt{2}$).

Thus after some mathematical reasoning we can prove that x is a real number. ■

Definition 6.2.6. A cut or Dedekind cut of the real line is a pair of nonempty subsets L and R of $\mathbb{R}$ such that $L \cup R = \mathbb{R}$ and for every $x \in L$ and $y \in R$, $x < y$. In terms of geometry, L is the left-hand set and R is the right-hand set.

Example 6.2.3. If $(-\infty, 1] \cup (1, \infty) = \mathbb{R}$, then $L = (-\infty, 1]$ and $R = (1, \infty)$

Theorem 6.2.6 (Completeness Axiom of $\mathbb{R}$). Let L and R define the cut of the real line. Then there is one and only one real number z such that for every $x \in L$ and $y \in R$, $x \leq z \leq y$.

Example 6.2.4. We have earlier proved that $\sqrt{2}$ is not a rational number and observe here that $(-\infty, \sqrt{2}) \cup (\sqrt{2}, \infty) \neq \mathbb{R}$, but $(-\infty, \sqrt{2}) \cup \{\sqrt{2}\} \cup (\sqrt{2}, \infty) = \mathbb{R}$. So by the Dedekind theorem $\sqrt{2}$ is a real number.

Thus, from the above discussion we may conclude that $\mathbb{R}$ is complete **BUT** $\mathbb{Q}$ is not.

6.3 Functions

Definition 6.3.1 (Function). A function f from a set A into a set B , denoted by $f : A \rightarrow B$, is a rule that assigns to each element $x \in A$ a **unique** element $y \in B$, and we write $y = f(x)$.

Or more precisely, A function f from a set A into a set B , denoted by $f : A \rightarrow B$, is a subset f of the cartesian product $A \times B$ such that for each $x \in A$ there exists a **unique** $y \in B$, and we write $y = f(x)$. Set A is called the **domain** of f and the set $\{y \in B : y = f(x)\}$ is called the **range** of f .

Example 6.3.1. The equation $y = 2x + 1$ defines a function but $x^2 + y^2 = 1$ does not.

Definition 6.3.2 (Monotone function). A function f is said to be increasing if $f(x_1) \leq f(x_2)$ for $x_1 \leq x_2$ and decreasing if $f(x_1) \geq f(x_2)$ for $x_1 \leq x_2$. A function is said to be monotone if it is either increasing or decreasing.

Definition 6.3.3 (Injective/one-one function). A function $f : A \rightarrow B$ is said to be one-one if $x_1 \neq x_2$, then $f(x_1) \neq f(x_2)$.

Definition 6.3.4 (Surjective/onto function). A function f is said to be onto if $f(A) = B$.

Definition 6.3.5 (Bijective function/1-1 correspondence). A function f is said to be bijective if it is both injective and surjective.

Definition 6.3.6 (Inverse function). A function, denoted by f^{-1} , is said to be the inverse of f if f is one-one. Thus f^{-1} is related to f as follows:

$$x = f^{-1}(y) \quad \text{if and only if} \quad y = f(x).$$

PROBLEM PLUS 6

1.

2.

Chapter 7

Sequence and Sequence of Functions

7.1 Sequence

Definition 7.1.1 (Sequence). A sequence in $\mathbb{R}$ is a function from the set $\mathbb{N}$ of natural numbers into the set $\mathbb{R}$ of real numbers. Thus, if $X : \mathbb{N} \rightarrow \mathbb{R}$ is a sequence, then the value of X at $n \in \mathbb{N}$ is denoted by x_n rather than $X(n)$. We denote sequence by the notations:

$$X, \quad (x_n), \quad < x_n > .$$

What is the difference between the **SET** and **SEQUENCE**?

Definition 7.1.2 (Convergence of Sequence). A real number x is said to be a limit of a sequence x_n , written as $x_n \rightarrow x$ or $\lim_{n \rightarrow \infty} x_n = x$ if for every $\epsilon > 0$ there exists a natural number $K := K(\epsilon)$ such that $|x_n - x| < \epsilon$ for all $n \geq K$. If x is the limit of a sequence, we say that x_n converges to x or x_n has the limit x . If a sequence has a limit we say that the sequence is convergent; if it has no limit, we say that the sequence is divergent.

Example 7.1.1. (i) $x_n = \frac{1}{n}$ is a convergent sequence.

(ii) $x_n = \frac{2n}{n+2}$ is a convergent sequence.

(ii) $X = < 2, 4, 6, 8, \dots >$ is a divergent sequence.

(iv) $x_n = (-1)^n$ is a bounded but divergent sequence.

Theorem 7.1.1. Every convergent sequence is bounded.

Example 7.1.2. $x_n = \frac{2n}{n+2}$

Theorem 7.1.2 (Archimedean Property). If $x \in \mathbb{R}$, then there exists $n_x \in \mathbb{N}$ such that $x < n_x$.

This suggests that $\mathbb{N}$, the set of natural numbers is unbounded.

Example 7.1.3. Show that $\lim(1/n) = 0$.

Solution: For given $\epsilon > 0$, $1/\epsilon > 0$. Hence by Archimedean Property there exists a natural number $K := K(\epsilon)$ such that $1/\epsilon < K$, then for any $n \in \mathbb{N}$ such that $n \geq K \implies 1/\epsilon < K \leq n$ so that $1/n < \epsilon$. Therefore, if $n \geq K$, then $|\frac{1}{n} - 0| = \frac{1}{n} < \epsilon$.

Theorem 7.1.3. The sum, difference, scalar multiple, product, and division (not always) of two convergent sequences are convergent.

Theorem 7.1.4 (Squeeze Theorem). If $x_n \leq y_n \leq z_n$ for $n \geq K$ and both $x_n, z_n \rightarrow x$, then $y_n \rightarrow x$

Example 7.1.4. Use the above theorem to show that $\lim(\frac{\sin n}{n}) = 0$

Theorem 7.1.5 (Absolute Convergence). If $|x_n| \rightarrow 0$, then $x_n \rightarrow 0$.

Example 7.1.5. Use the above theorem to show that $\lim(\frac{(-1)^n}{n}) = 0$

Theorem 7.1.6 (Ratio Test). Let x_n be a sequence of positive real numbers such that $L = \lim(x_{n+1}/x_n)$ exists. If $L < 1$, then x_n converges and $\lim(x_n) = 0$.

Example 7.1.6. Use the above theorem to show that $\lim(n!/n^n) = 0$

Theorem 7.1.7 (Monotone Convergence Theorem). A monotone sequence of real numbers is convergent iff it is bounded. Further, if $\langle x_n \rangle$ is a bounded increasing sequence, then $x_n \rightarrow \sup\{x_n\}$ and if $\langle x_n \rangle$ is a bounded decreasing sequence, then $x_n \rightarrow \inf\{x_n\}$

Example 7.1.7. Consider the sequence $x_{n+1} = (x_n + a/x_n)/2$ where $a > 0$, $x_1 > 0$. (This calculates the square roots of a). Here $x_n - x_{n+1} \geq 0 \implies x_{n+1} \leq x_n$ for all $n \geq 2$. It follows from Monotone Convergence Theorem that $x = \lim(x_n)$ exists. So $x = (x + a/x)/2 \implies x = \sqrt{a}$.

Theorem 7.1.8 (The Bolzano-Weierstrass Theorem). A bounded sequence of real numbers has a convergent subsequence

Example 7.1.8. Find a convergent subsequence of $x_n = (-1)^n$

Definition 7.1.3 (Cauchy Sequence). A sequence of real numbers x_n is said to be a Cauchy sequence if for every $\epsilon > 0$ there exists a natural number $K := K(\epsilon)$ such that $|x_m - x_n| < \epsilon$ for all $m, n \geq K$.

Theorem 7.1.9 (Cauchy Convergence Criterion). A sequence of real numbers is convergent if and only if it is Cauchy sequence.

Example 7.1.9. $x_n = \frac{1}{n}$ is a Cauchy sequence.

7.2 Sequence of Functions

What we have studied so far is the **sequence of constants** i.e., sequence of constant functions. In this section we shall discuss about the sequence of arbitrary functions. Therefore, the **sequence of function** is a sequence whose terms are *functions* rather than real numbers. Sequences of functions arise naturally in real analysis and are especially useful in obtaining approximations to a given function and defining new functions from known ones.

Let's begin with an example:

Example 7.2.1. Consider the sequence of functions $f_n : A = [0, 1] \rightarrow \mathbb{R}$ defined by $f_n(x) := x^n$. We have $f_n(0) = 0$ for all n and $f_n(x) \rightarrow 0$ if $x < 1$, but $f_n(1) = 1$ for all n . Thus, $f_n(x)$ converges to a function $f(x)$ where

$$f(x) := \begin{cases} 0 & \text{for } 0 \leq x < 1 \\ 1 & \text{if } x = 1, \end{cases}$$

Note that the limit of the sequence of functions depend on x that is the sequence of functions converges **pointwise**. Also note that the functions in the sequence are **continuous** but the limit function is **not**.

Now let's go through the following example:

Example 7.2.2. Consider the sequence of functions $f_n : \mathbb{R} \rightarrow \mathbb{R}$ defined by $f_n(x) := \frac{\sin x}{n}$. We have $f(x) := \lim_{n \rightarrow \infty} \frac{\sin x}{n} = (\sin x) \lim_{n \rightarrow \infty} \frac{1}{n} = (\sin x) \cdot 0 = 0$ for all $x \in \mathbb{R}$.

Here note that the limit of the sequence of functions does not depend on x that is the sequence of functions converges **uniformly**. Also note that the functions in the sequence are **continuous** and so **does** the limit function.

Therefore according to these examples the following two definitions are in order:

Definition 7.2.1 (Pointwise Convergence). Let $\langle f_n \rangle$ be a sequence of functions on $B \subseteq \mathbb{R}$ to $\mathbb{R}$, let $A \subseteq B$, and $f : A \subseteq B \rightarrow \mathbb{R}$. Then the sequence $\langle f_n \rangle$ converges pointwise on A to f if, for EACH $x \in A$, $\lim_{n \rightarrow \infty} f_n(x) = f(x)$.

In other words, $f_n \rightarrow f$ (**pointwise**) on A if for every $\epsilon > 0$ and for **each** $x \in A$, there exists a natural number $K := K(\epsilon, x)$ such that if $n \geq K$

$$|f_n(x) - f(x)| < \epsilon.$$

Definition 7.2.2 (Uniform Convergence). Let $\langle f_n \rangle$ be a sequence of functions on $B \subseteq \mathbb{R}$ to $\mathbb{R}$, let $A \subseteq B$, and $f : A \subseteq B \rightarrow \mathbb{R}$. Then the sequence $\langle f_n \rangle$ converges uniformly on A to f if, for ALL $x \in A$, $\lim_{n \rightarrow \infty} f_n(x) = f(x)$.

In other words, $f_n \rightarrow f$ (**uniformly**) on A if for every $\epsilon > 0$ and for **all** $x \in A$, there exists a natural number $K := K(\epsilon)$ (depending on ϵ but **not on** x) such that if $n \geq K$

$$|f_n(x) - f(x)| < \epsilon.$$

Notations:

- $f_n \rightarrow f$ (**pointwise**) on $A \Rightarrow f_n \rightarrow f$ on A or $f_n(x) \rightarrow f(x)$ for $x \in A$

- $f_n \rightarrow f$ (**uniformly**) on $A \Rightarrow f_n \rightrightarrows f$ on A or $f_n(x) \rightrightarrows f(x)$ for $x \in A$

Example 7.2.3. Discuss the uniform convergence of the sequence $\langle f_n \rangle$ where $f : A = [0, 1] \rightarrow \mathbb{R}$ is defined by $f_n(x) = \frac{x}{n}$, $n \in \mathbb{N}$.

Solution: First find the pointwise convergence and then the uniform convergence. Clearly, $f_n(x) \rightarrow f = 0$ on A . We claim that this convergence is uniform as well. To this end, let $\epsilon > 0$, then $1/\epsilon > 0$, by Archimedean theorem, $\exists K \in \mathbb{N}$ such that $1/\epsilon < K \Rightarrow 1/K < \epsilon$. Now, if $n \geq K$, then

$$\begin{aligned} |f_n(x) - f(x)| &= \left| \frac{x}{n} - 0 \right| \\ &= \frac{x}{n} \\ &\leq \frac{1}{n} \quad \text{for all } x \in A \\ &< \frac{1}{K} \\ &< \epsilon \end{aligned}$$

Therefore, $f_n \rightrightarrows f$ on A

Example 7.2.4. Discuss the uniform convergence of the sequence $\langle f_n \rangle$ where $f : A = [0, 1] \rightarrow \mathbb{R}$ is defined by $f_n(x) = 1 - \frac{x}{n}$, $n \in \mathbb{N}$.

Solution: First find the pointwise convergence and then the uniform convergence. Clearly, $f_n(x) \rightarrow f = 1$ on A . We claim that this convergence is uniform as well. To this end, let $\epsilon > 0$, then $1/\epsilon > 0$, by Archimedean theorem, $\exists K \in \mathbb{N}$ such that $1/\epsilon < K \Rightarrow 1/K < \epsilon$. Now, if $n \geq K$, then

$$\begin{aligned} |f_n(x) - f(x)| &= \left| 1 - \frac{x}{n} - 1 \right| \\ &= \frac{x}{n} \\ &\leq \frac{1}{n} \quad \text{for all } x \in A \\ &< \frac{1}{K} < \epsilon \end{aligned}$$

Therefore, $f_n \rightrightarrows f$ on A

Example 7.2.5. Discuss the uniform convergence of the sequence $\langle f_n \rangle$ where $f : A = [0, 1] \rightarrow \mathbb{R}$ is defined by $f_n(x) = \frac{x}{1+nx}$, $n \in \mathbb{N}$.

Solution: First find the pointwise convergence and then the uniform convergence. Clearly, $f_n(x) \rightarrow f = 0$ on A . We claim that this convergence is uniform as well. To this end, let $\epsilon > 0$, then $1/\epsilon > 0$, by Archimedean theorem, $\exists K \in \mathbb{N}$ such that $1/\epsilon < K \Rightarrow 1/K < \epsilon$. Now, if $n \geq K$, then

$$\begin{aligned} \left| f_n(x) - f(x) \right| &= \left| \frac{x}{1+nx} - 0 \right| < \left| \frac{x}{nx} \right| = 1/n \quad \text{for all } x \in A \\ &< 1/K < \epsilon \end{aligned}$$

Therefore, $f_n \Rightarrow f$ on A

Lemma 7.2.1. A sequence of functions f_n on $B \subseteq \mathbb{R}$ does not converge uniformly on $A \subseteq B$ to a function $f : A \rightarrow \mathbb{R}$ iff for some $\epsilon_0 > 0$ there is a subsequence f_{n_k} of f_n and a sequence x_k in A such that

$$\left| f_{n_k}(x_k) - f(x_k) \right| \geq \epsilon_0 \quad \text{for all } k \in \mathbb{N}.$$

Example 7.2.6. Discuss the uniform convergence of the sequence $\langle f_n \rangle$ where $f_n : A = [0, \infty) \rightarrow \mathbb{R}$ is defined by $f_n(x) = \frac{nx}{1+n^2x^2}$, $n \in \mathbb{N}$.

Solution: First find the pointwise convergence and then the uniform convergence. Clearly, $f_n(x) \rightarrow f = 0$ on A . We claim that this convergence is not uniform on A . To this end, let $\epsilon > 0$, and let $n_k = n$, $x_k = 1/n$, then

$$\left| f_{n_k}(x_k) - f(x_k) \right| = \left| f_n(1/n) - f(1/n) \right| = 1/2 \geq \epsilon \quad \text{for all } n \in \mathbb{N}.$$

Therefore, f_n is not uniformly convergent to f on A

Theorem 7.2.2 (Interchange of Limit and Continuity). Let $\langle f_n \rangle$ be a sequence of functions on a set $A \subseteq \mathbb{R}$ and suppose that f_n converges uniformly on A to a function $f : A \rightarrow \mathbb{R}$. Then f is continuous on A .

Theorem 7.2.3 (Interchange of Limit and Derivative). (J. R. Marsden [7]) Let $\langle f_n \rangle$ be a sequence of differentiable functions on a set $A = (a, b) \subseteq \mathbb{R}$ converging pointwise to f on A . Suppose that the derivatives $\langle f'_n \rangle$ are continuous and converge uniformly to a function g . Then f is differentiable and $f' = g$, i.e.,

$$\lim_{n \rightarrow \infty} f'_n = \left(\lim_{n \rightarrow \infty} f_n \right)'$$

Theorem 7.2.4 (Interchange of Limit and Integral). Let $\langle f_n \rangle$ be a sequence of functions that are (Riemann) integrable on $A = [a, b]$ and suppose that $\langle f_n \rangle$ converges uniformly on A to a function f . Then f is (Riemann) integrable on A and $\int_a^b f(x)dx = \lim_{n \rightarrow \infty} \int_a^b f_n(x)dx$ i.e.,

$$\lim_{n \rightarrow \infty} \int_a^b f_n(x)dx = \int_a^b \lim_{n \rightarrow \infty} f_n(x)dx$$

Theorem 7.2.5 (Bounded Convergence Theorem). *Let $\langle f_n \rangle$ be a sequence of (Riemann) integrable functions on $A = [a, b]$ and suppose that $\langle f_n \rangle$ converges on A to a (Riemann) integrable function f . Suppose also that there exists $M > 0$ such that $|f_n(x)| \leq M$ for all $x \in A$. Then*

$$\int_a^b f(x)dx = \lim_{n \rightarrow \infty} \int_a^b f_n(x)dx.$$

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Chapter 8

Series and Series of Functions

8.1 Series

Definition 8.1.1 (Series). Sum of the terms of an infinite sequence is called a series. Given a series $\sum_{n=1}^{\infty} x_n = \sum x_n = x_1 + x_2 + x_3 + \cdots$, let s_n denote its n -th partial sum:

$$s_n = \sum_{k=1}^n x_k = x_1 + x_2 + x_3 + \cdots + x_n.$$

If the sequence s_n is convergent, i.e. if x is a real number such that $\lim(s_n) = x$, then the series $\sum x_n$ is called **convergent** and we write

$$\lim_{n \rightarrow \infty} \sum_{k=1}^n x_k = \sum_{k=1}^{\infty} x_k = x_1 + x_2 + x_3 + \cdots = x.$$

The number x is called the **sum** of the series. Otherwise, the series is **divergent**.

Note that $\sum_{k=1}^{\infty} x_k = \lim_{n \rightarrow \infty} \sum_{k=1}^n x_k$.

Theorem 8.1.1. The geometric series

$$\sum_{n=1}^{\infty} ar^{n-1} = a + ar + ar^2 + \cdots$$

is convergent if $|r| < 1$ and its sum is

$$\sum_{n=1}^{\infty} ar^{n-1} = \frac{a}{1-r} \quad |r| < 1$$

If $|r| \geq 1$, the series is divergent.

Example 8.1.1. Test whether the series $\sum_{n=1}^{\infty} 2^{2n} 3^{1-n}$ is convergent or divergent.

Solution: $\sum_{n=1}^{\infty} 2^{2n} 3^{1-n} = \sum_{n=1}^{\infty} 4(4/3)^{n-1}$ is a geometric series with $a = 4$ and $r = 4/3 > 1$. So, the series is divergent.

Theorem 8.1.2. The p -series $\sum_{n=1}^{\infty} \frac{1}{n^p}$ is convergent if $p > 1$ and divergent if $p \leq 1$. When $p = 1$ the series is called the **harmonic series**.

Theorem 8.1.3. If the series $\sum_{n=1}^{\infty} x_n$ is convergent, then $\lim(x_n) = 0$. But the converse is not true in general, e.g., harmonic series.

Theorem 8.1.4 (The Test for Divergence). If $x_n \rightarrow \infty$ or $x_n \nrightarrow 0$ then the series $\sum_{n=1}^{\infty} x_n$ is divergent.

Example 8.1.2. Test whether the series $\sum_{n=1}^{\infty} \frac{n^2}{5n^2+4}$ is convergent or divergent.

Solution: Here $x_n = \frac{n^2}{5n^2+4} \rightarrow 1/5 \neq 0$ so The Test for Divergence implies that the series is divergent.

Theorem 8.1.5. The sum, difference, and scalar multiple of two convergent series are convergent.

Example 8.1.3. Find the sum of the series $\sum_{n=1}^{\infty} (\frac{3}{n(n+1)} + \frac{1}{2^n})$.

Solution: Here second series is a geometric series with $a = 1/2$ and $r = 1/2$, so $\sum_{n=1}^{\infty} \frac{1}{2^n} = \frac{a}{1-r} = 1$. The first series is $\sum_{n=1}^{\infty} \frac{3}{n(n+1)} = 3 \lim_{n \rightarrow \infty} \sum_{i=1}^n \frac{1}{i(i+1)} = \lim_{n \rightarrow \infty} (1 - \frac{1}{n+1}) = 3 \cdot 1 = 3$. Therefore the sum of the given series is $3 + 1 = 4$.

Theorem 8.1.6 (Cauchy Criterion for Series). A series $\sum x_n$ in $\mathbb{R}$ is convergent iff for each $\epsilon > 0$ there is a natural number $K := K(\epsilon)$ such that if $m > n \geq K$, then

$$|s_m - s_n| = |x_{n+1} + x_{n+2} + \cdots + x_m| < \epsilon.$$

Definition 8.1.2. We say that a series $\sum x_n$ is **absolutely convergent** if the series $\sum |x_n|$ is convergent in $\mathbb{R}$. A series is said to be **conditionally convergent** if it is convergent but not absolutely convergent.

Theorem 8.1.7. If a series is absolutely convergent, then it is convergent.

8.1.1 Tests for Absolute Convergence

Theorem 8.1.8 (Comparison Test). Let x_n and y_n be real sequences such that for some natural number K ,

$$0 \leq x_n \leq y_n \quad \text{for } n \geq K.$$

Then the convergence of $\sum y_n$ implies the convergence of $\sum x_n$ and the divergence of $\sum x_n$ implies the divergence of $\sum y_n$.

Example 8.1.4. Test the convergence of the series $\sum_{n=1}^{\infty} \frac{5}{2n^2+4n+3}$.

Solution: Note that $\frac{5}{2n^2+4n+3} < \frac{5}{2n^2}$ by the p -series $\sum \frac{1}{n^2}$ converges and hence by the Comparison Test the given series is convergent.

Theorem 8.1.9 (Limit Comparison Test). Let x_n and y_n be positive real sequences and $L = \lim(x_n/y_n)$

(a) If $L \neq 0$, then $\sum x_n$ is convergent iff $\sum y_n$ is convergent.

(b) If $L = 0$ and $\sum y_n$ is convergent, then $\sum x_n$ is convergent.

Example 8.1.5. Test the convergence of the series $\sum_{n=1}^{\infty} \frac{2n^2+3n}{\sqrt{5+n^5}}$.

Solution: Note that the dominant part of the numerator is $2n^2$ and the dominant part of the denominator is $\sqrt{n^5}$. This suggests taking $x_n = \frac{2n^2+3n}{\sqrt{5+n^5}}$, $y_n = \frac{2n^2}{\sqrt{n^5}} = \frac{2}{n^{1/2}}$, $\lim_{n \rightarrow \infty} \frac{x_n}{y_n} = \lim_{n \rightarrow \infty} \frac{2n^2+3n}{\sqrt{5+n^5}} \cdot \frac{n^{1/2}}{2} = 1$ Since $\sum y_n = 2 \sum 1/n^{1/2}$ is divergent (p -series with $p = 1/2 < 1$), the given series diverges by the Limit Comparison Test.

Theorem 8.1.10 (Root Test). Let x_n be a sequence in $\mathbb{R}$ and

$$r := \lim(|x_n|^{1/n}).$$

Then $\sum x_n$ is absolutely convergent if $r < 1$ and divergent if $r > 1$.

Example 8.1.6. Test the series $\sum_{n=1}^{\infty} \left(\frac{2n+3}{3n+2}\right)^n$

Solution: Root Test with $x_n = \left(\frac{2n+3}{3n+2}\right)^n$ gives: $\sqrt[n]{|x_n|} = \frac{2n+3}{3n+2} \rightarrow 2/3 < 1$ Thus, the given series converges by the Root Test.

Theorem 8.1.11 (Ratio Test). Let x_n be a sequence in $\mathbb{R}$ and

$$r := \lim(|x_{n+1}|/|x_n|).$$

Then $\sum x_n$ is absolutely convergent if $r < 1$ and divergent if $r > 1$.

Example 8.1.7. Test the series $\sum_{n=1}^{\infty} (-1)^n \frac{n^3}{3^n}$ for absolute convergence.

Solution: Ratio Test with $x_n = (-1)^n \frac{n^3}{3^n}$ gives: $|\frac{a_{n+1}}{a_n}| = |\frac{1}{3}(\frac{n+1}{n})^3| = |\frac{1}{3}(1 + 1/n)^3| \rightarrow \frac{1}{3} < 1$ Thus, by the Ratio Test, the given series is absolutely convergent and therefore convergent.

Theorem 8.1.12 (Raabe's Test). Let x_n be a sequence of nonzero real numbers and

$$r := \lim\left(n\left(1 - \frac{|x_{n+1}|}{|x_n|}\right)\right)$$

Then $\sum x_n$ is absolutely convergent if $r > 1$ and is not absolutely convergent if $r < 1$.

Theorem 8.1.13 (Integral Test). Let f be a continuous, positive decreasing function on $[1, \infty)$ and $x_n = f(n)$. Then if $\int_1^{\infty} f(x)dx$ is convergent (divergent), then $\sum x_n$ is convergent (divergent).

Example 8.1.8. Test the series $\sum_{n=1}^{\infty} \frac{\ln n}{n}$ for convergence.

Solution: The function $f(x) = (\ln x)/x$ is positive and continuous for $x > 1$ because the logarithm function is continuous. But it is not clear whether or not f is decreasing, so $f'(x) = \frac{1-\ln x}{x^2}$. Thus, $f'(x) < 0$ when $1 - \ln x < 0$, i.e., $x > e$. So f is decreasing when $x > e$. Here $\int_1^{\infty} \frac{\ln x}{x} dx = \lim_{t \rightarrow \infty} \int_1^t \frac{\ln x}{x} dx = \infty$ Therefore, by the Integral Test the given series is divergent.

8.1.2 Tests for Nonabsolute Convergence

Definition 8.1.3 (Alternating Series). An alternating series is a series whose terms are alternately positive and negative. The n -th term of an alternating series is defined by $x_n = (-1)^{n-1}y_n$, $x_n = (-1)^n y_n$, $x_n = (-1)^{n+1}y_n$ where $n \in \mathbb{N}$ and $y_n > 0$

Theorem 8.1.14 (Alternating Series Test). Let x_n be a decreasing sequence of positive real numbers with $\lim(x_n) = 0$. Then the alternating series $\sum (-1)^{n+1}x_n$ is convergent.

Example 8.1.9. Test the convergence of the series $\sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n}$, $\sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{\sqrt{n}}$.

8.2 Series of Functions

We have studied the series of constants(i.e. constant functions). He we shall study the series of functions rather than constants.

Definition 8.2.1 (Pointwise and Uniform Convergence of Series). Let the function f and the sequence of functions $\langle f_n \rangle$ be defined on $B \subseteq \mathbb{R}$ and $s_n = \sum_{k=1}^n f_k$ be the sequence of partial sums of the series $\sum_{n=1}^{\infty} f_n$ in $B \subseteq \mathbb{R}$.

Then if $s_n \rightarrow f$ (*pointwise*) on B (i.e., $s_n \rightarrow f$ on B), then $\sum_{n=1}^{\infty} f_n(x) \rightarrow f(x)$ for $x \in B$ and we write $\sum_{n=1}^{\infty} f_n(x) = f(x)$ (*pointwise*)

Then if $s_n \rightarrow f$ (*uniformly*) on B (i.e., $s_n \Rightarrow f$ on B), then $\sum_{n=1}^{\infty} f_n(x) \Rightarrow f(x)$ for $x \in B$ and we write $\sum_{n=1}^{\infty} f_n(x) = f(x)$ (*uniformly*)

Theorem 8.2.1 (Interchange of Limit and Sum). Let $\langle f_n \rangle$ be a sequence of functions on a set $A \subseteq \mathbb{R}$ and suppose that $\sum f_n$ converges uniformly on A to a function $f : A \rightarrow \mathbb{R}$. Then f is continuous on A and

$$\lim_{x \rightarrow x_0} \sum_{n=1}^{\infty} f_n(x) = \sum_{n=1}^{\infty} \lim_{x \rightarrow x_0} f_n(x).$$

Theorem 8.2.2 (Interchange of Sum and Derivative). (J. R. Marsden [7]) If $\langle f_n \rangle$ are differentiable functions on a set $A = (a, b) \subseteq \mathbb{R}$, the $\langle f'_n \rangle$ are continuous, $\sum_{n=1}^{\infty} f_n$ converge pointwise, and $\sum_{n=1}^{\infty} f'_n$ converges uniformly, then

$$\left(\sum_{n=1}^{\infty} f_n \right)' = \sum_{n=1}^{\infty} f'_n.$$

Theorem 8.2.3 (Interchange of Integral and Sum). Let $\langle f_n \rangle$ be a sequence of functions that are (Riemann) integrable on $A = [a, b]$ and suppose that $\langle f_n \rangle$ converges uniformly on A . Then we may interchange the order of integration and summation:

$$\int_a^b \left(\sum_{n=1}^{\infty} f_n(x) \right) dx = \sum_{n=1}^{\infty} \left(\int_a^b f_n(x) dx \right).$$

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Chapter 9

Limit and Continuity of a Function

9.1 Limit of a Function

Definition 9.1.1 (Cluster Point or Accumulation Point). Let $A \subseteq \mathbb{R}$. A point $c \in \mathbb{R}$ is called a cluster point of A if every δ -neighborhood $V_\delta(c) := (c - \delta, c + \delta)$ of c contains at least one point of A other than c , i.e.,

$$V_\delta(c) - \{c\} \cap A \neq \emptyset$$

Definition 9.1.2 (Limit Point). Let $A \subseteq \mathbb{R}$. A point $c \in \mathbb{R}$ is called a limit point of A if every δ -neighborhood $V_\delta(c) := (c - \delta, c + \delta)$ of c contains at least one point of A , i.e.,

$$V_\delta(c) \cap A \neq \emptyset$$

Example 9.1.1.

- (a) Let $A = (0, 1) \cup \{3\}$. Then the set of cluster points of A is $[0, 1]$ and the set of limit points of A is $[0, 1] \cup \{3\}$.
- (b) A finite set has no cluster points.
- (c) $\mathbb{N}$ has no cluster points.
- (d) $B = \{\frac{1}{n} : n \in \mathbb{N}\}$ has only one cluster point 0.
- (e) Let $S = \{x \in \mathbb{R} : x \in [0, 1] \text{ and } x \text{ is rational}\}$. Then all points of $[0, 1]$ are accumulation points of S .

Definition 9.1.3 ($\epsilon - \delta$: Definition of Limit of a Function). Let $A \subseteq \mathbb{R}$, and let c be a cluster point of A . We say that a real number L is a limit of f at c , written $\lim_{x \rightarrow c} f(x) = L$ or $f(x) \rightarrow L$ as $x \rightarrow c$ if, given any ϵ -neighborhood $V_\epsilon(L)$ of L , there exists a δ -neighborhood $V_\delta(c)$ of c such that if $x \neq c$ is any point of $V_\delta(c) \cap A$, then $f(x)$ belongs to $V_\epsilon(L)$.

In other words, L is a limit of f at c , written $\lim_{x \rightarrow c} f(x) = L$ or $f(x) \rightarrow L$ as $x \rightarrow c$, if given $\epsilon > 0$ there exists a $\delta := \delta(\epsilon) > 0$ such that if $0 < |x - c| < \delta$, then $|f(x) - L| < \epsilon$

Example 9.1.2. Apply $\epsilon - \delta$ definition of limit to illustrate that

$$\lim_{x \rightarrow 4} (2x - 2) = 6$$

Solution: Here $f(x) = 2x - 2$, $c = 4$, and $L = 6$.

Let $\epsilon > 0$. WANT to find a $\delta := \delta(\epsilon) > 0$ such that

if $0 < |x - c| < \delta$, then $|f(x) - L| < \epsilon$ i.e.,

if $0 < |x - 4| < \delta$, then $|f(x) - L| < \epsilon$

Now, $|f(x) - L| = |(2x - 2) - 6| = 2|x - 4| < 2\delta$

If we choose $\delta = \frac{\epsilon}{2} =: \delta(\epsilon)$, then

if $0 < |x - c| < \delta$, then $|f(x) - L| < \epsilon$

Therefore, $\lim_{x \rightarrow c} f(x) = L \Rightarrow \lim_{x \rightarrow 4} (2x - 2) = 6$

Theorem 9.1.1 (Sequential Criterion). Let $f : A \rightarrow \mathbb{R}$ and c be a cluster point of A ; then:

(i) $\lim_{x \rightarrow c} f(x) = L$ *if and only if*

(ii) for every sequence x_n in A that converges to c such that $x \neq c$ for all $n \in \mathbb{N}$, the sequence $f(x_n)$ converges to L .

Theorem 9.1.2 (Divergence Criterion). Let $f : A \rightarrow \mathbb{R}$ and c be a cluster point of A ; then:

(i) The function f does *not* have a limit at c

if and only if

(ii) $\exists$ a sequence $x_n \neq c$ for all $n \in \mathbb{N}$ such that the sequence x_n converges to c but the sequence $f(x_n)$ does *not* converge in $\mathbb{R}$

Example 9.1.3. Show that $\lim_{x \rightarrow 0} \frac{1}{x}$ does not exist in $\mathbb{R}$.

Solution: Here let $f(x) = \frac{1}{x}$ for $x > 0$. Take the sequence $x_n := 1/n$ for $n \in \mathbb{N}$, then $f(x_n) = n$ does not converge in $\mathbb{R}$. Hence by the Divergence Criterion the given sequence does not exist in $\mathbb{R}$.

9.2 Continuous Function

Definition 9.2.1 (Continuous Function). Let $f : A \subseteq \mathbb{R} \rightarrow \mathbb{R}$. We say that f is continuous at a point $c \in A$, written $\lim_{x \rightarrow c} f(x) = f(c)$ if, given any ϵ -neighborhood $V_\epsilon(f(c))$ of $f(c)$, there exists a δ -neighborhood $V_\delta(c)$ of c such that if $x \in V_\delta(c) \cap A$, then $f(x) \in V_\epsilon(f(c))$.

In other words, f is continuous at a point $c \in A$, written $\lim_{x \rightarrow c} f(x) = f(c)$ if, given any $\epsilon > 0$ there exists a $\delta := \delta(\epsilon, x) > 0$ such that if $|x - c| < \delta$, then $|f(x) - f(c)| < \epsilon$

Theorem 9.2.1 (Discontinuity Criterion). Let $f : A \rightarrow \mathbb{R}$ and $c \in A$; then:

(i) The function f is *discontinuous* at c

if and only if

(ii) $\exists$ a sequence x_n in A such that the sequence x_n converges to c , but the sequence $f(x_n)$ does *not* converge to $f(c)$.

Example 9.2.1.

- (a) $f(x) = x$ is continuous on $\mathbb{R}$.
- (b) $f(x) = x^2$ is continuous on $\mathbb{R}$.
- (c) $f(x) = 1/x$ is continuous on $A = (0, \infty)$.
- (d) $f(x) = 1/x$ is not continuous at 0.

Theorem 9.2.2 (Combination of Continuous Functions). The sum, difference, product, scalar multiple, and division (if the denominator is not zero) of two continuous functions are continuous.

Theorem 9.2.3 (Polynomial functions). are always continuous.

Definition 9.2.2 (Bounded Function). A function $f : A \subseteq \mathbb{R} \rightarrow \mathbb{R}$ is said to be bounded on A if there exists a constant $M > 0$ such that $|f(x)| \leq M$ for all $x \in A$.

Example 9.2.2.

- (a) $f(x) = x$ is bounded on $A = [-7, 2]$ but unbounded on $\mathbb{R}$.
- (b) $f(x) = 1/x$ is continuous on $A = (0, \infty)$ but not bounded on A . $f(x)$ is not even bounded when restricted to the set $B = (0, 1)$.

Theorem 9.2.4 (Boundedness Theorem). Let $I := [a, b]$ be a closed bounded interval and let $f : I \rightarrow \mathbb{R}$ be continuous on I . Then f is bounded on I .

Definition 9.2.3 (Absolute Extremum of a Function). Let $f : A \subseteq \mathbb{R} \rightarrow \mathbb{R}$ be a function. We say that f has an *absolute maximum on A* if there is a point $x^* \in A$ such that

$$f(x^*) \geq f(x) \quad \text{for all } x \in A.$$

We say that f has an *absolute minimum on A* if there is a point $x_* \in A$ such that

$$f(x_*) \leq f(x) \quad \text{for all } x \in A.$$

We say that x^* is an *absolute maximum point* for f on A , and that x_* is an *absolute minimum point* for f on A , if they exist.

Example 9.2.3. 1. Continuous function on a set A does not necessarily have an absolute maximum or an absolute minimum on the set.

- 2. $f(x) = 1/x$ has neither an absolute maximum nor an absolute minimum on the set $A = (0, \infty)$.
- 3. The same function has neither an absolute maximum nor an absolute minimum when restricted to the *open* set $B = (0, 1)$.
- 4. While the same function has *BOTH* an absolute maximum and an absolute minimum when restricted to the *closed set* $C = [0, 1]$.

5. The function $f(x) = x^2$ on $A = [-1, +1]$ has two points $x = \pm 1$ giving the absolute maximum and a single point $x = 0$ yielding the absolute minimum on A .
6. The constant function $f(x) = c$ is such that for $x \in \mathbb{R}$ is such that **EVERY** point of $\mathbb{R}$ is **BOTH** an absolute maximum and an absolute minimum point for f .

Theorem 9.2.5 (Maximum-Minimum(Maximin) Theorem). Let $I := [a, b]$ be a closed bounded interval and let $f : I \rightarrow \mathbb{R}$ be continuous on I . Then f has an absolute maximum and an absolute minimum on I .

Theorem 9.2.6 ((Bolzano's) Intermediate Value Theorem). Let I be any interval and let $f : I \rightarrow \mathbb{R}$ be continuous on I . If $a, b \in I$ and if $k \in \mathbb{R}$ satisfies $f(a) < k < f(b)$, then there exists a point $c \in I$ between a and b such that $f(c) = k$.

Corollary 9.2.7. Let $I = [a, b]$ be a closed, bounded interval and let $f : I \rightarrow \mathbb{R}$ be continuous on I . If $k \in \mathbb{R}$ is any number satisfying

$$\inf f(I) \leq k \leq \sup f(I),$$

then there exists a number $c \in I$ such that $f(c) = k$.

The following corollary provides the **Location of Roots**:

Corollary 9.2.8. Let I be any interval and let $f : I \rightarrow \mathbb{R}$ be continuous on I . If $a < b$ are numbers in I such that $f(a) < 0 < f(b)$ (or such that $f(a) > 0 > f(b)$), then there exists a point $c \in (a, b)$ such that $f(c) = 0$.

1.

2.

Chapter 10

Differentiation

Definition 10.0.4 (The Derivative). Let $f : I \rightarrow \mathbb{R}$ where $c \in I$, an interval. We say that a real number L is the **derivative of f at c** if for any given number $\epsilon > 0$ there exists a number $\delta(\epsilon) > 0$, then

$$\left| \frac{f(x) - f(c)}{x - c} - L \right| < \epsilon.$$

In this case we say that f is **differentiable at c** , and we write $f'(c)$ for L .

In other words, the derivative of f at c is given by the limit

$$f'(c) = \lim_{x \rightarrow c} \frac{f(x) - f(c)}{x - c}$$

Theorem 10.0.9. If $f : I \rightarrow \mathbb{R}$ has a derivative at $c \in I$, then f is continuous at c .

Is the converse true? **WHY?**

Theorem 10.0.10. The sum, difference, scalar multiple, product, and division(not always) of two differentiable functions are differentiable.

Theorem 10.0.11 (Rolle's Theorem). Let $f : I = [a, b] \rightarrow \mathbb{R}$ be continuous on a closed interval $[a, b]$ and differentiable on the open interval (a, b) , and that $f(a) = f(b) = 0$. Then there exists at least one point c in (a, b) such that $f'(c) = 0$.

The Mean Value Theorem relates the values of a function to values of its derivative which is stated as follows.

Theorem 10.0.12 (Mean Value Theorem). Let $f : I = [a, b] \rightarrow \mathbb{R}$ be continuous on a closed interval $[a, b]$ and differentiable on the open interval (a, b) . Then there exists at least one point c in (a, b) such that $f'(c) = \frac{f(b) - f(a)}{b - a}$.

One can easily deduce Rolle's Theorem from Mean Value Theorem. Now we shall present the **Taylor's Theorem** which is simply the generalization of the **Mean Value Theorem**.

Theorem 10.0.13 (Taylor's Theorem). Let $f : I = [a, b] \rightarrow \mathbb{R}$ be a function such that f and its derivatives up to order n are continuous on a closed interval $[a, b]$ and $f^{(n+1)}$ exists on the open interval (a, b) . If $x_0 \in I$, then for any x in I there exists a point c between x and x_0 such that

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \cdots + \frac{f^{(n)}(x_0)}{n!}(x-x_0)^n + \frac{f^{(n+1)}(c)}{(n+1)!}(x-x_0)^{(n+1)}$$

where the last term

$$R_n(x) = \frac{f^{(n+1)}(c)}{(n+1)!}(x-x_0)^{(n+1)}$$

is called the remainder.

Theorem 10.0.14 (Taylor's Inequality or The Remainder Estimation Theorem). If $|f^{(n+1)}(x)| \leq M$ for all $x \in I$, and a number $x_0 \in I$, then

$$|R_n(x)| \leq \frac{M}{(n+1)!}|x-x_0|^{n+1}.$$

Theorem 10.0.15. If $n \rightarrow \infty$ then $R_n(x) \rightarrow 0$.

Hence the Taylor's Theorem gives us the Taylor's series:

Theorem 10.0.16 (Taylor's Series).

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \cdots + \frac{f^{(n)}(x_0)}{n!}(x-x_0)^n + \cdots$$

Taylor's Series evaluated at $x_0 = 0$ is called the **Maclaurin's series** which is given as follows:

$$f(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \cdots + \frac{f^{(n)}(0)}{n!}x^n + \cdots$$

Example 10.0.4.

- Expand $f(x) = e^x$.
- The function $f(x) = \sin x$ about the point $x_0 = \pi/2$.

Theorem 10.0.17 (L'Hospital's Rule). Suppose that f and g are differentiable and $g'(x) \neq 0$ near x_0 (except possibly at x_0). Suppose that $\lim_{x \rightarrow x_0} f(x) = 0$ and $\lim_{x \rightarrow x_0} g(x) = 0$ or that $\lim_{x \rightarrow x_0} f(x) = \pm\infty$ and $\lim_{x \rightarrow x_0} g(x) = \pm\infty$ (In other words, we have an indeterminate form of type $\frac{0}{0}$ or $\frac{\infty}{\infty}$.)

Then

$$\lim_{x \rightarrow x_0} \frac{f(x)}{g(x)} = \lim_{x \rightarrow x_0} \frac{f'(x)}{g'(x)}.$$

If the limit on the right side exists (or is ∞ or $-\infty$).

Example 10.0.5. • Find $\lim_{x \rightarrow 1} \frac{\ln x}{x-1}$

- Find $\lim_{x \rightarrow 0} \frac{\tan x - x}{x^3}$
- Find $\lim_{x \rightarrow 2} \frac{x^2 - 4}{x - 2}$

- 1.
- 2.

Chapter 11

Riemann Integration

Riemann Integration

- 1.
- 2.

Appendix A

Reviews

Reviews

$$(A.1) \quad a + b + c$$

$$\begin{aligned} &+ d + e + f \\ &+ g + h + i \\ &+ j + k + l \end{aligned}$$

$$\frac{\partial u}{\partial x} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^3 u}{\partial x^3} + \frac{\partial^4 u}{\partial y^4} = 0$$

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$$z = \underbrace{x}_{\text{real}} + \underbrace{iy}_{\text{imaginary}}$$

Everything will be printed in W H A T E V E R you like.

~~stack-out~~

1. Shah Noor

2 Happy

First Name: Mohammad

Second Name: Shah

Third Name: Noor

Spouse: Happy

Son: Rashad

‘quote’ “quote”
reverse margin note ¹

margin
note

¹This chapter summarizes the important commands

```

1 function ycal = rk4_msn(f,x0,xn,y0,n)
2 % This function calculates solves the
3 % ode y'=f(x,y),y(x0)=y0 using runge-kutta 4th order method
4
5 n = 50 ; x0=0 ; xn=2 ; x1=x0 ; xnp1=xn ; np1= n + 1 ;h
6 =(xnp1-x1)/np1 ; x = linspace(x1, xnp1, np1); ycal(1) = 1/10 ;
7
8 for k = 1 : n
9     f1 = exp(-2*x(k)) - 2*ycal(k) ;
10    f2 = exp(-2*(x(k)+h/2)) - 2*(ycal(k) +h*f1/2) ;
11    f3 = exp(-2*(x(k)+h/2)) - 2*(ycal(k) +h*f2/2) ;
12    f4 = exp(-2*(x(k)+h)) - 2*(ycal(k) +h*f3) ;
13    sf = f1 + 2 * f2 + 2 * f3 + f4 ;
14    ycal(k+1) = ycal(k) + h*sf/6 ;
15 end yexact = (0.1 + x).*exp(-2*x) ; a = [x' ycal' yexact'] ;
16 b=a(:,1)
17 %plot(x,ycal, 'r', x,yexact, 'b'); grid on;
18 plot(a(:,1),a(:,2), 'r', a(:,1),a(:,3), 'b'); grid on;
19 xlabel('x');ylabel('ycal and yexact') return

```

- 1.
- 2.

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